## Series 988

## User's Manual

Includes 986, 987, 988 and 989


## 1/8 DIN Microprocessor-Based Temperature/Process Controller

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## Series 988 User's Manual

Includes 986, 987, 988 and 989

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# Introduction to the Watlow Series 988 Controllers 

Figure Int. 1 The Series 988 Controllers.


Watlow's Series 988 controllers set a new standard in the controller industry by packing an impressive array of features into an $1 / 8$-DIN package. No other controller offers the flexibility, compact size and durability of the Series 988 . It can control a wide variety of temperature and process applications, with a broad range of input and output options that allow control of virtually any process variable.

The Series 988 is the only 1/8 DIN controller that can provide single-unit cascade control of a process. Its other features include heater current monitoring, remote set point input, ratio control and valve control through slidewire feedback. The Series 988 also delivers expanded auto-tuning capabilities, increased alarm functionality and several unique control algorithms.

When we refer to the "Series 988" controller, we refer also to the horizontal and low-voltage versions of the Series 988: the 986, 987, 988 and 989. We recommend that you read all of this manual's introduction to familiarize yourself with the conventions and content of this manual and the steps to setting up a Series 988 controller. Make sure you understand the "Caution" and "Warning" symbols we use in the book.

NOTE:
The 12-digit number is printed on the top of the stickers on each side of the controller's case and on the righthand or top circuit board.

NOTE:
The Menu Overview
in the Appendix shows all the
menus and prompts.

## Using this Manual

This manual provides the information you will need to install and operate a Series 988 controller.

If you need information about Series 988 configurations and model numbers, refer to the Appendix of this manual or, for more detailed information, to Optimizing Your Process System with the Series 988 Controller: An Application Guide for the Watlow Series 988 Family.

If your Series 988 controller will be used for data communications, you will also need our communications manual, Data Communications with the Watlow Series 988 Family of Controllers (green cover).

Series 988 controllers are calibrated in the factory, but if you need to do periodic calibration you will need our calibration manual, Calibrating Watlow Process Controllers, (blue cover).

This manual explains the five steps of setting up a Series 988 controller:

1. Set and document all of the DIP switches, if applicable: Chapter 1.
2. Mount the controller: Chapter 2.
3. Wire and document the controller wiring: Chapter 2.
4. Configure and document the controller software: Chapters 3-6.
5. Run, test and adjust your application. Update documentation.

Chapters 7 and $\underline{8}$ and the Appendix provide detailed advice, definitions and specifications along with application examples to help you optimize the safety and performance of your application. Use the Table of Contents and Index to find specific information.

## Document Every Step

The Series 988 provides powerful and complex features. Carefully document each step of the setup and any subsequent changes. This will make it much easier to change, adjust and troubleshoot your application.

Make the configuration documentation available to engineers and technicians, on all shifts, who may need to work with the Series 988. We provide space in this manual to record configurations. You may prefer to photocopy the blank forms and keep them in a separate binder. However you maintain your documentation, be sure to replace all old copies of the documentation with updated versions whenever the controller configuration is changed.

## Notes, Cautions and Warnings

We use note, caution and warning symbols throughout this book to draw your attention to important operational and safety information.

A bold text "NOTE" marks a short message in the margin to alert you to an important detail.

A bold text "CAUTION" safety alert appears with information that is important for protecting your equipment and performance. Be especially careful to read and follow all cautions that apply to your application.

A bold text "WARNING" safety alert appears with information that is important for protecting you, others and equipment from damage. Pay very close attention to all warnings that apply to your application.

The $₫$ symbol (an exclamation point in a triangle) precedes a general CAUTION or WARNING statement.

The symbol (a lightning bolt in a triangle) precedes an electric shock hazard CAUTION or WARNING safety statement.

## Technical Assistance

If you encounter a problem with your Watlow controller, review all of your configuration information for each step of the setup to verify that your selections are consistent with your applications.

If the problem persists after checking all the steps, you can get technical assistance by calling Watlow Controls at (507) 454-5300, between 7 a.m. and 5 p.m. CST, and asking for an applications engineer. When you call have the following information on hand: the controller's model number (the 12-digit number is printed on the top of the stickers on each side of the controller's case and on the right-hand or top circuit board); your user's manual; all configuration information; and the Diagnostics Menu readings.

## We Value Your Feedback

Your comments and suggestions on this manual are welcome. Please send them to, Technical Writer, Watlow Controls, 1241 Bundy Blvd., P.O. Box 5580, Winona, MN 55987-5580 or call (507) 454-5300 or fax (507) 4524507.(1233)

## Chapter 1 Hardware Setup

## DIP Switch Locations and Functions

The Watlow Series 988 has at least one and as many as six dual in-line package (DIP) switches inside the controller, depending on the model number. They allow users to configure the controller for a variety of input sensors, to provide power for external signal conditioners or to lockout front panel access to some functions.

To set any DIP switch:

- Remove the controller from the case by pressing firmly on the two release tabs on one side or the top of the bezel until they unsnap. Then firmly press the two release tabs on the opposite side or the bottom of the control until they unsnap. You will need to gently rock the bezel back and forth to release it from the chassis.
- Use the illustrations on the following pages to locate and set each DIP switch.

Figure 1.1 - Press the release tabs to remove the controller chassis.


NOTE:
The Input 2 DIP switch is mounted upside down.

1. Set the input DIP switches to match the sensors you are using in your application. Only controllers with model number 98_ 2 _ - -or 98 _2_ _-_ _ _ _ have an input DIP switch.


NOTE:
Only controllers with the indicated model numbers have these DIP switches.

RTD (100 $\Omega$ )


Input 2
(98

Input 1
_) (98
$-2$
$\qquad$ --- - -
thermocouple: R, S or B

thermocouple: J, K, T, N, E, C, D, Pt2


Figure 1.2 Input DIP switches.


NOTE:
For other voltages or current settings contact the factory.
2. Set DIP switches for outputs equipped with an external signal conditioner power supply. Only controllers with model number 98_ _-
 _-_T_ _ have an external signal conditioner power supply.


Figure 1.3 -
External signal conditioner power supply DIPs.
3. When the DIP switches are set, gently insert the controller chassis into the case and push it firmly into place until all four tabs snap into place.


CAUTION:
The lockout DIP switch makes the Setup and Factory menus unavailable. Configure all the Setup and Factory menus before locking them out. Failure to do so could result in damage to equipment in the event of a setup error.

Figure 1.4 -
Lockout DIP switch.
4. The lockout DIP switch hides the Setup Menus (Input, Output, Global and Communications) and the Factory Menus (Panel Lockout, Diagnostics and Calibration). All units have a lockout DIP switch.
no hardware lockout (Switch 1 has no effect.)
lockout Setup and Factory menus (Switch 1 has no effect.)


Control Chassis Top View (986 \& 988) Left-side View (987 \& 989)



## Chapter 2 Installation and Wiring

NOTE:
Space panel cutouts at least 1.66 inches (42.2mm) apart.

NOTE:
Adjustable mounting brackets can be side-mounted.

NOTE:
Holes can be cut in the panel using a Greenlee 1/8 DIN Hydraulic Kit \#60068 (punch \#60069, die \#60070).

Figure 2.1 Series 988 and Series 989 dimensions and terminal number layout.



## Installing the Series 988

Installing and mounting requires access to the back of the panel.

1. Make a panel cutout using the panel cutout dimensions from the previous page.
2. To remove the controller chassis from its case, press in firmly on the two tabs on one side or the top of the bezel until they unsnap, then unsnap the two tabs on the opposite side or the bottom. Pull the chassis out of the case by gently rocking it.

## NOTE:

Removing the controller chassis from its case makes mounting easier.

Figure 2.2 -
Side and top view.



CAUTION:
Follow the installation procedure exactly to guarantee a proper NEMA 4X seal. Make sure the gasket between the panel and the rim of the case is not twisted and is seated properly. Failure to do so could result in damage to equipment.
the mounting collar over the back of the control.
4. Loosen the mounting bracket screws enough to allow for the mounting collar and panel thickness. Place each mounting bracket into the mounting slots (head of the screw facing the back of the controller). Push each bracket backward then down to secure it to the control case. To guarantee a proper NEMA 4X seal, Series 986 and 988 units (vertical) must have the mounting brackets located on either side of the unit. When installing Series 987 and 989 units (horizontal) the brackets must be on the top and bottom of the unit.
5. Make sure the case is seated properly. Tighten the installation screws firmly against the mounting collar to secure the unit. To ensure a NEMA 4X seal, there should be no space between the bezel and panel. Overtightening the screws will distort the case and make it difficult to remove or replace the controller.
6. Make sure the inside gasket is seated properly and not twisted. Insert the controller chassis into its case and press the bezel until all four tabs snap.
7. To release the mounting brackets, loosen the mounting bracket screws and push the brackets forward, then pull it up and out.


WARNING:
To avoid potential electric shock, use National Electric Code (NEC) safety practices when wiring and connecting this unit to a power source and to electrical sensors or peripheral devices. Failure to do so could result in injury or death.

NOTE:
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

Figure 2.4 Power wiring.

## Wiring the Series 988

Wiring options depend on the model number and DIP switch settings. Check the terminal designation stickers on either side of the controller and compare your model number to those shown here and with the model number breakdown on the inside back cover of this manual.

## Input-to-output Isolation

The Series 988 uses optical isolation between the analog inputs and the controller outputs/digital input. This isolation provides a 500V~ (ac) barrier to prevent ground loops when using grounded sensors and/or peripheral equipment.

Here is a breakdown of the isolation barriers:

- Analog inputs 1 and 2 are grouped together.
- Outputs 1 through 4 and the standard event input are grouped together. This does not apply to Output 4 when configured as communications.
- The digital communications output (4) is separate from the above groups.

Power Wiring

100 to $240 \mathrm{~V} \approx$ (ac/dc) nominal, (85 to 264 actual)

## Vertical Package

Horizontal Package
98 으﹎ $\qquad$ $98 \underline{9}$ -$----$ $---$
,
 -

24 to $28 \mathrm{~V} \approx(\mathrm{ac} / \mathrm{dc})$ nominal, (20 to 30 actual)
Vertical Package
Horizontal Package$-{ }^{-}$ $\qquad$
$----$ $98 \underline{7}_{-}^{-}$ ---${ }^{-}$

## Sensor Installation Guidelines



CAUTION:
The Series 988 will not function with two grounded thermocouple inputs. Avoid using a grounded thermocouple for both input 1 and input 2. Failure to follow this guideline could result in damage to equipment.

NOTE:
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

Maintain isolation between input 1 and input 2 to prevent a ground loop. A ground loop may cause incorrect readings, dashes across the upper display or the display of error codes.

Thermocouple input: Extension wire for thermocouples must be of the same alloy as the thermocouple itself to limit errors.

Using grounded thermocouples for both input 1 and input 2 may create ground loop problems. To correct this problem, replace at least one of the grounded thermocouples with an ungrounded thermocouple. If the application requires grounded thermocouples, use an isolated transmitter, such as a Watlow Gordon 5702 isolated transmitter.

RTD (100 $\Omega$ ) input: Each $1 \Omega$ of lead wire resistance can cause a $+2^{\circ} \mathrm{C}$ error when using a two-wire RTD. A three-wire RTD sensor overcomes this problem. All three wires must have the same electrical resistance (i.e., same gauge, same length, multi-stranded or solid, same metal).

Process input: Isolation must be maintained between input 1 and input 2. If both input 1 and input 2 are used as process inputs, a separate power supply and transmitter must be used for each input. Output option T (external signal conditioner power supply) can be used to supply power for only one input.

## Wiring Example



## WARNING:

To avoid potential electric shock, use National Electric Code (NEC) safety practices when wiring and connecting this unit to a power source and to electrical sensors or peripheral devices. Failure to do so could result in injury or death.


WARNING:
Install high or low temperature limit control protection in systems where an over temperature fault condition could present a fire hazard or other hazard. Failure to install temperature limit control protection where a potential hazard exists could result in damage to equipment, property and injury to personnel.


WARNING:
To avoid damage to property and equipment, and/or injury of loss of life, use National Electric Code (NEC) standard wiring practices to install and operate the Series 988. Failure to do so could result in such damage, and/or injury or death.

Figure 2.6 -
System wiring example.



1
WARNING:
To avoid damage to property and equipment, and/or injury of loss of life, use National Electric Code (NEC) standard wiring practices to install and operate the Series 988. Failure to do so could result in such damage, and/or injury or death.


NOTE:
Sketch in your application on this page or a copy of it. See wiring examples in this chapter and in the Appendix.

Figure 2.7 -
Wiring notes.

Figure 2.8a - Thermocouple or $0-50 \mathrm{mV}$ (high impedance)

## NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

Thermocouple only
98 _ _ $\mathbf{1}_{\text {_ }}$ $\qquad$ (no DIP switches)

Universal signal conditioner 98 $\qquad$ $\underline{2}$ $\qquad$ - - - - -

Input impedance: $20 \mathrm{M} \Omega$
Input impedance: $20 \mathrm{M} \Omega$
J, K, T, N, C, E, D, Pt2 $0-50 \mathrm{mV}$ DIP Settings

$\qquad$
$\qquad$
Figure 2.8 B - RTD (2- or 3-wire) ( $100 \Omega$ )


Figure $2.8 \mathrm{c}-0-5 \mathrm{~V}=1-5 \mathrm{~V}=$ or $0-10 \mathrm{~V}=$ (dc) Process
Universal signal conditioner

Input impedance: $10 \mathrm{~K} \Omega$


Figure $2.8 \mathrm{~d}=\mathbf{0 - 2 0 m A}$ or $\mathbf{4 - 2 0 m A}$ Process

Universal signal conditioner
98 $\qquad$ - 2 $\qquad$ - - -

Input impedance: $7 \Omega$


NOTE:
Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

Figure 2.9a - Thermocouple or 0-50mV (high impedance)
Thermocouple only
98 _ _ _ $\mathbf{1}_{\text {_ }}$
 (no DIP switches)

Universal signal conditioner 98 _ _ _ $\underline{\mathbf{2}}_{\text {_ }}$ - _-

Input impedance: $20 \mathrm{M} \Omega$

$$
\begin{gathered}
\text { J, K, T, N, C, E, D, Pt2, } \\
0-50 \mathrm{mV} \text { DIP Settings }
\end{gathered}
$$



Figure 2.9b - RTD (2- or 3-wire) (100 $\Omega$ )


Figure $2.9 c-0-5 \mathrm{~V}=1-5 \mathrm{~V}=$ or $0-10 \mathrm{~V}=$ (dc) Process


98 _ _ _ _ $\mathbf{2}_{\text {_ _ _ _ _ }}$

Input impedance: $10 \mathrm{~K} \Omega$


Figure $2.9 \mathrm{~d}=\mathbf{0}-20 \mathrm{~mA}$ or $\mathbf{4 - 2 0 m A}$ Process

Universal signal conditioner
$98_{\__{-}}{ }_{-}^{\mathbf{2}} \underline{Z}_{-}{ }_{-}{ }_{-}$
Input impedance: $7 \Omega$


NOTE:
See Chapter 8 for information on slidewire feedback.

NOTE:
A process output cannot be installed on output 1 when using a current transformer input.

NOTE:
Successful installation requires five steps:

- Model number and software choice
(Appendix);
- DIP switch set-
tings (Chapter 1);
- Sensor match
(Chapter 2 and
Appendix);
- Sensor installation
(Chapter 2); and
- Wiring (Chapter 2).

Figure 2.10a - Slidewire Feedback or Potentiometer Input

98 _ _ _ $\mathbf{3}_{\text {_ _ _ _ _ _ }}$


Figure 2.10b - Current Transformer Input

The current transformer must be purchased separately. See Appendix for Watlow current transformer part numbers.

Systems that use more than 50 Amps need an interstage transformer. For example, if you use a 300A current transformer, part \#16-0073, and an interstage transformer, part \#160176, the 300A current transformer provides a 5A signal to the interstage transformer. In turn, the transformer sends a 20 mA maximum signal to the controller.


3 -phase using 2 current transformers

Figure 2.10c — Digital Event Input 2

$$
98_{Z_{-}}^{-} \underline{5}_{Z_{-}^{-}}^{-{ }_{-}}
$$

open $0-3 \mathrm{~V}=$ (dc) Event Input 2 off closed $14-36 \mathrm{~V}=$ (dc) Event Input 2 on


## NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix); - DIP switch settings (Chapter 1);
- Sensor match
(Chapter 2 and
Appendix);
- Sensor installation
(Chapter 2); and
- Wiring (Chapter 2).

Figure 2.11a - Digital Event Input 1

Available on all units.
open $14-36 \mathrm{~V}=$ (dc) Event Input 1 off closed $0-3 V=$ (dc) Event Input 1 on


## NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch set-
tings (Chapter 1);
- Sensor match
(Chapter 2 and Appendix);
- Sensor installation
(Chapter 2); and
- Wiring (Chapter 2).

Figure 2.12a - AC Outputs

Solid-state Relay with Contact Suppression
98 $\qquad$
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay with Contact Suppression
(Suppression between NO and COM contacts only)
98 $\qquad$ - _ _ D D

- _ _ _ -

Form C, 5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$
Electromechanical Relay without Contact Suppression 98 $\qquad$ - $-\quad \underline{E}$ . - _ _ _ -

Form C, 5 amps off-state impedance: $31 \mathrm{M} \Omega$


## Solid-state Relay without Contact Suppression

98 $\qquad$ - _ _ K K - _ _ _ _
0.5 amps, off-state impedance: $31 \mathrm{M} \Omega$

## Figure 2.12b - Switched DC, Open Collector

```
98 _ _ - _ _ C- _- _ _ _ _
```

Maximum voltage: 42V=.. (dc)
Maximum current: 1A


Figure $2.12 \mathrm{c}=0-20 \mathrm{~mA}$ and $4-20 \mathrm{~mA}$ Process


Maximum load impedance: $800 \Omega$


Figure 2.12d $-0-5 \mathrm{~V}=, 1-5 \mathrm{~V}=$ and $0-10 \mathrm{~V}=$ (dc) Process

Minimum load impedance: $1 \mathrm{~K} \Omega$


Figure 2.13a-AC Outputs

NOTE:
Successful installation requires five steps:

- Model number and software choice (Appendix); - DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

NOTE:
Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-01470000.

NOTE:
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

Solid-state Relay with Contact Suppression
98 $\qquad$ - _ _ _ B - $\qquad$
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay with Contact Suppression
(Suppression between NO and COM contacts only)
98
_ - _ _ _ D
D
_ - - -
Form C, 5 amps, minimum off-state impedance: $20 \mathrm{~K} \Omega$
Electromechanical Relay without Contact Suppression
98 $\qquad$ - _-E $\qquad$
Form C, 5 amps off-state impedance: $31 \mathrm{M} \Omega$
Solid-state Relay without Contact Suppression
98 $\qquad$ - _ _ _ K - $\qquad$
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$


Figure 2.13b - Switched DC, Open Collector


Figure $2.13 \mathrm{c}-\mathbf{0}-20 \mathrm{~mA}$ and $4-20 \mathrm{~mA}$ Process

$$
98_{--_{-}^{-}} \mathbf{F}_{-}^{-} \mathbf{F}_{----}
$$

Maximum load impedance: $800 \Omega$


Figure 2.13d $-0-5 \mathrm{~V}=, 1-5 \mathrm{~V}=$ and $0-10 \mathrm{~V}=(\mathrm{dc})$ Process

98 $\qquad$
Minimum load impedance: $1 \mathrm{~K} \Omega$


Figure 2.13e - External Signal Conditioner Power Supply


NOTE:
Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

NOTE:
Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-01470000.

NOTE:
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

Figure 2.14a-AC Outputs

Solid-state Relay with Contact Suppression
98 $\qquad$ - - - - B $\qquad$
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$


Electromechanical Relay without Contact Suppression 98 $\qquad$ - - ---- J J _ - _ Form A or B, 5 amps , off-state impedance: $31 \mathrm{M} \Omega$

Solid-state Relay without Contact Suppression 98 $\qquad$ - _ _ _ K $\qquad$
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$


Figure 2.14b - Switched DC

98 $\qquad$
 C $\qquad$
Minimum load resistance: $500 \Omega$


Figure 2.14c - Process Retransmit

0-20mA, 4-20mA, Load impedance: $600 \Omega$ max.
98 $\qquad$ - M $\qquad$
$\mathbf{0 - 5 V}=, \mathbf{1 - 5 V}=, \mathbf{0 - 1 0 V}=(\mathrm{VDC})$, Load impedance: $500 \Omega \mathrm{~min}$.
98 $\qquad$ N $\qquad$


Figure 2.14d - External Signal Conditioner Power Supply



NOTE:
Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match
(Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

Figure 2.15a - AC Outputs

Solid-state Relay with Contact Suppression
98 _ _ - _ _ _ _ _ _ B _ _
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay with Contact Suppression
(Suppression between NO and COM contacts only)
98 _ _ - _ _ _ _ - _ $\mathbf{D}$ _ _ _
Form C, 5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$
Electromechanical Relay without Contact Suppression


Form C, 5 amps , off-state impedance: $31 \mathrm{M} \Omega$
Solid-state Relay without Contact Suppression
98
8 _ _ - _ _ K $\qquad$
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$

## NOTE:

Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-01470000.

NOTE:
Input-to-output isolation is defeated when the external transmitter power supply is used to power a signal conditioner connected to input 1 or input 2.

98 $\qquad$ - -$\mathbf{T}_{\text {_ }}$

NOTE:
See Chapter 1 for power supply DIP switch information.


For data communications wiring refer to Data Communications with the Watlow Series 988 Family of Controllers.

# Chapter 3 Front Panel and Display Loop 

## Keys and Displays

## Upper Display

Indicates the actual process value, prompt parameter value or error code.

## DEV LED

When lit, the lower display shows the most recent deviation unit from the set point.

## \% OUT LED

When lit, the lower display shows the current percent output.

## Up-arrow Key

Increases the value or changes the parameter in the upper display (except for set point changes in the Display Loop, which occur in the lower display). Hold the key down to increase the value rapidly. New data takes effect in five seconds or when the Mode key or Display key is pressed.

## Down-arrow Key

Decreases the value or changes the parameter in the upper display (except for set point changes in the Display Loop, which occur in the lower display). Hold the key down to decrease the value rapidly. New data takes effect in five seconds or when the Mode key or Display key is pressed.

## Up + Down Keys

Press simultaneously for three seconds to go to the Setup Menu. Continue to press both keys for another three seconds to go to the Factory Menu. Access to the Setup and Factory menus can be disabled with lockout DIP switch.


## Mode Key

Enters new data and steps to the next prompt in the current menu.

## Mode + Up-arrow Keys

Hold the Mode key then press the Up-arrow key to move backwards through the current menu. Scrolling stops when you reach the top of the menu.

## Lower Display

Indicates the set point, deviation, percent power, temperature unit, menu prompt name or alarm code.

## L1, L2, L3, L4

These LED's indicate when output $1,2,3$ or 4 are active. Outputs can be configured as:
Ot1 Control
Ot2 Control or Alarm
Ot3 Alarm or Retransmit
Ot4 Alarm or Communications (flashes on transmit and receive)

## Display Key

Pressing this key enters the Display Loop. Press the Display key at any time to return to this loop. The next page has more information on the Display Loop.

## Auto/Man Key

In Manual mode the lower display shows percent output. Pressed once, it clears any latched alarm. If pressed again within five seconds it will toggle between Auto and Manual mode.

## Auto/Man LED

Lit when the control is in Manual operation. Press the Auto/Man key twice to enter Automatic operation. When blinking, press the Auto/Man key to toggle between Auto and Manual. After five seconds without pressing the Auto/Man key, the LED stops blinking and returns to its previous state.

Figure 3.1 -
Series 988 Keys and Displays

## NOTE:

For information on input $1 \square$ in 1 and input 2 inc ranges, refer to Chapter 4.

NOTE:
If $\quad$ no is selected
for inc), in the Input Menu, the Pr 2] prompt will not appear.

Figure 3.2 -
The Display Loop

## Display Loop

The Display Loop is the "home" state of the Series 988 controller. Pressing the Display key Isman returns the controller to the Display Loop from any prompt in any menu. The controller automatically returns to the Display Loop from any menu when a minute passes without any keys being pressed.

988 current input 2 reading Pr 2 input 2 process (appears only if controller equipped with input 2 hardware)
(1ssLav 988 current input 1 reading
(IssLAA $\rightarrow 988$ deviation from set point, process 1 minus set point 1 (DEV light on)
Osfan 988 current input 1 reading
100 percent output (\%OUT light on)
988 current input 1 reading
${ }^{\circ} \mathrm{C}$ units selected (units, ${ }^{\circ} \mathrm{F}$ or ${ }^{\circ} \mathrm{C}$ )

## Chapter 4 The Setup Menus

NOTE:
When navigating through menus, outputs will be disabled.

NOTE:
Press the Display
key oishlav to return to
the Display Loop from any point in any menu.

Figure 4.1 -
Navigating the Setup Menus.

NOTE:
The lockout DIP switch hides the Setup Menus. See Chapter 1.

## Navigating the Setup Menus

To reach the Setup Menus, begin in the Display Loop and press both the Uparrow $\triangle$ and Down-arrow $\nabla$ keys for three seconds. The Setup Menu prompt SEE will appear in the lower display, and the Input Menu prompt inPt will appear in the upper display. The four Setup Menus are: Input inPt; Output OtPE; Global 9LbL; and Communications [OT7. Use the Up-arrow $\triangle$ or Down-arrow $\triangle$ key to select a menu and the Mode key mode to step through a menu. The Communications Menu appears only on units equipped with the data communications option.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 988 returns to the Setup Menu prompt $5 E E$. Use the Up-arrow $\triangle$ and Down-arrow $\nabla$ keys to select the next menu, or use the Mode key mode to advance through the same menu again. To move backwards through the menu hold the Mode key moos down and press the Uparrow key $\boldsymbol{\sim}$. Use the Up-arrow $\boldsymbol{\sim}$ or Down-arrow key to change the prompt setting.

Refer to the Appendix for model number options. For information about communications and the communications prompts, refer to the supplemental manual Data Communications with the Watlow Series 988 Family of Controllers.

(1) Begin in the Display Loop, and press the Up-arrow $\triangle$ and Down-arrow keys simultaneously to reach the Setup Menus.

(2) Press the Up-arrow key to select one of the Setup Menus.

## Setup-Input

Reaching the Input Menu

(3) Select the Input Menu, then press the Mode key mods to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{C}$ or the Down-arrow key $چ$ to select one of the prompt values.
*Prompts may not appear, depending on controller configuration.


Figure 4.2 -
The Input Menu.

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 $d E[1$ and Decimal 2 dE[己] parameters in the Input Menu.


CAUTION: Changing the value of in il changes most other prompts to the factory default values. Document all settings before changing sensor type. Verify the correct sensor type before making a change. Failure to follow this guideline could result in damage to equipment or property. Document all settings before changing sensor type.

## in 1

Input 1 continued on next page.

## Input Prompts

When you are in the Setup menus, the Series 988 displays the menu selection ( InPt, OLPL, SLbL or [ $\cap \cap \boldsymbol{O}$ ) in the upper display, and $5 E L$ in the lower display.

The Up-arrow $\boldsymbol{\triangle}$ or Down-arrow key $\boldsymbol{\sim}$ Mode key moos to display the prompt in the lower display and its value in the upper display. Use the Up-arrow $\boldsymbol{\sim}$ or Down-arrow key to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key moom.

## Input 1

Select sensor type for input 1. This selection must match the sensor type connected to terminals 8,9 and 10. See Appendix for more information about sensors.

- Changing the value of in 1 changes all other prompts to the factory default values, except the Communications and Lockout menus, the $\left[\_F\right.$ prompt in the Global Menu and the $d F L$ prompt in the Calibration Menu. If you change the value, the default warning $d F L t$ will flash in the upper display.
- Changes do not take effect automatically after five seconds; you must press the Mode key moos to enter the sensor type change and advance to the next prompt.
in 1 This prompt always appears.



## Setup-Input

in i
Input 1 continued from previous page.

RTD

| Input 1 DIP | 4-20mA | 0-20mA | $0-5 \mathrm{~V}=$ | 1-5V $=$ | $0-10 \mathrm{~V}=$ (dc) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $0^{1}{ }^{3}$ | 4-20 | $0-20$ | 0-5 | 1-5 | $0-10$ |
| $\square \square \square$ | in 1 | in 1 | in 1 | in 1 | in 1 |

process
dEE 1

## Decimal 1

Select the decimal point location for process type input 1 data. This prompt, in conjunction with the Range Low and Range High prompts, allows you to format and limit units of measure for process 1 .

- All prompts with units of measure related to input 1 will display in the selected decimal format.
- This affects propbands, alarm set points, process set points, calibration offsets, deadbands and ranges.
dE[ 1 This prompt appears only if you have set input $1 \square$ in to a process input or to a thermocouple input set to $0-50 \mathrm{mV}$.



## ril

rHi

NOTE:
These values do not affect the low or the high set point limit for process alarms.

NOTE:
When high impedance $0-50$ is selected for input 1 the range high for both $0^{\circ}[$ and of can be extended to 9999. The range low when ${ }^{\circ}[$ is selected can be extended to -999.


Range Low 1 and Range High 1 continued on next page.

## Range Low 1 and Range High 1

Select the low and high limits for input 1. These prompts limit the adjustment range for the set points. The default values are the same as the limits of the sensor you selected by setting the input 1 DIP switch and selecting a value for Input $1 \square$ in 1 .

- Process inputs are scaled by these values. Range high is the value displayed when the maximum process signal is present at the input. Range low is the value displayed when the minimum process signal is present at the input.

$$
\begin{array}{ll}
\text { Example: } & \text { Set } \operatorname{\text {in}~} \text { to } 4-20 \mathrm{~mA} . \\
\text { Set } r i \text { to } 100 . \\
\text { Set } r H \text { it } 500 . \\
\text { A } 4 \mathrm{~mA} \text { input will display } ~ & 100 . \\
\text { A 12mA input will display } 300 . \\
& \text { A 20mA input will display } 500 .
\end{array}
$$

- The low and high values of each sensor type are listed on the specifications page of the Appendix.
- Choose between Fahrenheit and Celsius at the [_F prompt in the Global Menu.
rLIrHi These prompts always appear.

|  |  |  |  |
| :---: | :---: | :---: | :---: |
|  | rit rHi | rit rHi |  |
| $\pm$ | 32]... 1500 | 0... 816 | $\begin{aligned} & 98--1---\quad \text { or } \\ & 98-2-2--2 \end{aligned}$ |
| in | rli rHi | rLi rHi |  |
| (K) |  |  |  |
| H | -328]..2500 | -200...1371 |  |
| $t$ | -328]... 750 | -200)... 399 |  |
| $\square$ | $32 . .2372$ | $0 . .1300$ |  |
| $\boldsymbol{E}$ | -328... 1470 | -200)... 799 |  |
| (W5) |  |  |  |
| [ | 32]...4200 | 0)..2316 |  |
| (W3) |  |  |  |
| d | 32]..4200 | 0...2316 |  |
| Ptz | 32...2543 | 0).. 1395 |  |
| high impedance $0-50$ | -993... 999 | -573... 573 |  |



Range Low 1 and Range High 1 continued from previous page.

NOTE:
These values do not affect the low or the high set point limit for process alarms.


## CRL

## Calibration Offset 1

Offset the input 1 signal by a positive or negative value. This allows you to compensate for lead resistance, sensor errors or other factors.
[AL 1 This prompt always appears.


## RTD (100 2 ) Calibration Curve 1

Select the calibration curve for the RTD 1 input. The RTD input uses either the European (DIN, $0.003850 \Omega / \Omega /{ }^{\circ} \mathrm{C}$ ) or the Japanese (JIS, $0.003916 \Omega / \Omega /{ }^{\circ} \mathrm{C}$ ) linearization standard.
$r t d i$ This prompt appears only if you have set $\square$ in 1 to $\square \mathbf{r d}$ or rt.d.


Ftr 1

## Software Filter 1

Select the filter time constant, in seconds, for input 1. This smooths a rapidly changing input signal for display or control purposes.

- Select a positive value to filter only the display.
- Select a negative value to filter the input signal.
- Set the value to 0 to disable the filter.

FEr I This prompt always appears.


Lint

## Linearization 1

## Select square root linearization for input 1.

Lin $!$ This prompt appears only if you have set in 1 to a process input or to a thermocouple set to $0-50 \mathrm{mV}$.


NOTE:
See Chapter 8 for more information on input linearization.

## inc

CAUTION:
Changing the value of inc changes most other prompts to the factory default values. Document all settings before changing sensor type. Verify the correct sensor type before making a change. Failure to follow this guideline could result in damage to equipment or property. Document all settings before changing sensor type.

## NOTE:

If $n 0$ is selected for inc none of the other input 2 prompts will appear.

## Input 2

Select sensor type for input 2. This selection must match the sensor type connected to terminals 18, 19 and 20. See Appendix for more information about sensors.

- Changing the value of in己 changes all other prompts to the factory default values, except the Communications and Lockout menus, the $\left[\_F\right.$ prompt in the Global Menu and the $d F L$ prompt in the Calibration Menu. If you change the value, the default warning $d F L E$ will flash in the upper display.
- Changes do not take effect automatically after five seconds; you must press the Mode key mode to enter the sensor type change and advance to the next prompt.
in己 This prompt and other Input 2 prompts appear only on controllers



RTD

| Input 2 DIP |  | 4-20mA | 0-20mA | 0-5V $=$ | $1-5 \mathrm{~V}=$ | 0-10V $=$ ( dc ) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | no | 4-20 | $0-20$ | 0-5 | 1-5 | $0-10$ |
|  | inc | inc | inc | $\square$ inc | inc | inc |

process
thermocouple

thermocouple


## inc

Input 2 continued on next page.

## Setup-Input

## inc

Input 2 continued from previous page.

rSp

## Remote Set Point

Enable a remote set point signal.
$r$ SP This prompt appears only if the controller is equipped with input 2 hardware and if $\square$ ind is not set to no and if [ntl (in the Global Menu) is set to nor.


## dEC己

## $r$ L

rHC


Range Low 2 and Range High 2 continued on next page.

## Decimal 2

Select the decimal point location for process type input 2 data. This prompt, in conjunction with the Range Low and Range High prompts, allows you to format and limit units of measure for process 2.

- All prompts with units of measure related to input 2 will display in the selected decimal format.
- This affects propbands, alarm set points, process set points, calibration offsets, deadbands and ranges.
$d E[2]$ This prompt appears only if you have set input $2 \square$ inc to a process input, [urr or a thermocouple input set to $0-50 \mathrm{mV}$.



## Range Low 2 and Range High 2

Select the low and high limits for input 2. These prompts limit the adjustment range for the set points. The default values are the same as the limits of the sensor you selected by setting the input 2 DIP switch and selecting a value for Input $2 \square$ inc .

- Process inputs are scaled by these values. Range high is the value displayed when the maximum process signal is present at the input. Range low is the value displayed when the minimum process signal is present at the input.

Example: Set 4 ind to 4-20 mA.
Set $r(2)$ to 100.
Set rH ) to 500 .
A 4 mA input will display 100 .
A 12 mA input will display 300 .
A 20 mA input will display 500 .

- The low and high values of each sensor type are listed on the specifications page of the Appendix.
- Choose between Fahrenheit and Celsius at the [ [ F prompt in the Global Menu.
$r$ L $\quad \mathrm{rHC}$ These prompts appear only if the controller is equipped with input 2 hardware and with Input $2 \square$ ind not set to $\square$ nor $\varepsilon, 2$.


## $r$ le <br> rH2

Range Low 2 and Range High 2 continued from previous page.

NOTE:
These values do not affect the low or the high set point limit for process alarms.

NOTE:
When high impedance $0-50$ is selected for input 1 the range high for both $O_{[ }$[ and of can be extended to (9999. The range low when
${ }^{\circ}[$ is selected can be extended to -999.

|  |  | Default $\quad$ Default <br> $\downarrow$ $\downarrow$ |  |
| :---: | :---: | :---: | :---: |
|  | rLC rH2 | rLD rHC |  |
| $\square$ | 32].. 1500 | (0).. 816 | $\begin{aligned} & 98 \\ & 98 \\ & 98-2 \end{aligned}$ |
| ,inc | ric rel | rLE rHE |  |
| (K) |  |  |  |
| H | -328 ...2500 | -200 .. 1371 |  |
| $t$ | -328]... 750 | -200]... 399 |  |
| $\square$ | 32...2372 | $01 . .1300$ |  |
| $\boldsymbol{E}$ | -328].. 1470 | -200 ... 799 |  |
| (W5) |  |  |  |
| [ | 32]..4200 | 0]..2316 |  |
| (W3) |  |  |  |
| d | 32]..4200 | 0 0...2316 |  |
| Ptz | 32]..2543 | 0 0... 1395 |  |
| high impedance $0-50$ | -999... 999 | -573]... 573 |  |
| $\square$ | 32]..3200 | 0 0... 1760 | 98__-2_--_-_ only |
| 5 | 32]..3200 | 0).. 1760 |  |
| $b$ | 32]..3300 | 0 0... 1816 |  |
| rtd | -328]...1472 | -200]... 800 |  |
| ret.d | -99.9]..999.9 | -73.3]..537.7 |  |


| 4-20 | -999...9999 | units |
| :---: | :---: | :---: |
| 0-20 | -999...9999 | units |
| 0-5 | -999...9999 | units |
| 1-5 | -999...9999 | units |
| 0-10 | -999...9999 | units |
| 0-50 | -999...9999 | units |
| 0100 | -999...9999 | units |
| slidewire SL id | 100)..1200 | ohms |
| current Curr | 0).. 50 | amps |
| potentiometer POE | $01 . .1200$ | ohms |

Lrni

## Learn Low

Write the low-end resistance of the slidewire potentiometer to the range low 2 parameter.
$L r n L$ This prompt appears only on controllers equipped with input 2


NOTE:
See Chapter 8 for more information on slidewire feedback.

## LrnH

NOTE:
See Chapter 8 for more information on slidewire feedback.

## Learn High

Write the high-end resistance of the slidewire potentiometer to the range low 2 parameter.
$L \subset \cap H$ This prompt appears only on controllers equipped with input 2 hardware and with Input 2 inc ] set to $5 \mathrm{~L}, \mathrm{~d}$ or $P \mathrm{OL}$.


## [RLD] <br> Calibration Offset 2

Offset the input 2 signal by a positive or negative value. This allows you to compensate for lead resistance, sensor errors or other factors.
[RL工 This prompt appears only if the controller is equipped with input 2 hardware and if $\operatorname{in} \boldsymbol{Z}$ is not set to $n$ or or $\mathcal{E}$ ? .

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ |  | Minimum | Default $\downarrow$ | Max. setting/range |
| :---: | :---: | :---: | :---: | :---: |
| of |  | -999 |  | ... 999 |
| $\frac{C_{-F}}{(G)}$ |  | [ALC] | [ALC] | [ALC] |
| OF | \& rt.d | -99.9 | 0.0 | ... 99.9 |
| $\underset{(G-F}{(G i o b a l ~ M e n u)}$ | $\frac{\text { ind }}{\text { (Input Menu) }}$ | [ALE] | [ALL | [ALL |
| ${ }^{\circ} \mathrm{C}$ |  | -555 | 0 | ... 555 |
| $\underset{(G-F}{c}$ |  | [CALL | [CALC] | [ALC] |
| ${ }^{\circ} \mathrm{C}$ | \& rt.d | -55.5 | 0.0 | ... 55.5 |
| $\frac{c-f}{c}$ | $\sin 2$ | [CAL 2 | [CALE | [CAL |
| a process input is selected |  | $\frac{-999}{[\text { CAL }}$ | $\begin{array}{\|r\|} \hline 0 \\ \hline \text { CAL } \end{array}$ | $\cdots \frac{999 \text { units }}{\text { CALL }}$ |

## $r t d 己$ RTD Calibration Curve 2

Select the calibration curve for the RTD 2 input. The RTD input uses either the European (DIN, $0.003850 \Omega / \Omega /{ }^{\circ} \mathrm{C}$ ) or Japanese (JIS, $0.003916 \Omega / \Omega /{ }^{\circ} \mathrm{C}$ ) linearization standard.
$r$ td This prompt appears only on controllers equipped with input 2 hardware and with $\quad$ ind set to rtd or rt.d.
Default
$\downarrow$
$\frac{\text { din }}{\text { rtds }} \frac{\text { jis }}{\text { rtds }}$

## Ftr己

## Linc

NOTE:
See Chapter 8 for more information on input linearization.

## Software Filter 2

Select the filter time constant, in seconds, for input 2. This smooths a rapidly changing input signal for display or control purposes.

- Select a positive value to filter only the display.
- Select a negative value to filter the input signal.
- Set the value to $\quad \mathbf{0}$ to disable the filter.

Ftr $]$ This prompt appears only on controllers equipped with input 2 hardware and with $\quad$ inc not set to $n 0$ or $\boldsymbol{E} \boldsymbol{I}$ ].


## Linearization 2

## Select square root linearization for input 2.

$[$ in $\boldsymbol{L}$ This prompt appears only if you have set Input $2 \square$ in己 to a process input or to a thermocouple input set to $0-50 \mathrm{mV}$.
Default
$\downarrow$

| no | root |
| ---: | ---: |
| Lind | Lind |

## Hunt Hunt

NOTE:
See Chapter 8 for more information on slidewire feedback.

Set the deadband, as a percentage of output, to keep the valve from hunting.

- The slidewire hysteresis SHYS setting provides additional control over a valve.

Hunt This prompt appears only if the controller is equipped with slidewire hardware (98_ _-_3_ _- _ ) and with $\square$ inc set to 5 L id.


## 5H45 Slidewire Hysteresis

Set the inner hysteresis, the point at which the valve output turns off.

- The figure below illustrates the interaction between slidewire hysteresis 5HYS and hunt Hunt.

SHY5 This prompt appears only if the controller is equipped with slidewire hardware (98__-_3__-__) and with Input $2 \square$ inc set to 5 L , d
NOTE:
See Chapter 8 for more information on slidewire feedback.

Figure 4.17 Hunt and slidewire inner hysteresis.


## Reaching the Output Menu

(1) Begin in the Display Loop, and press the Up-arrow and Downarrow keys simultaneously for three seconds to reach the Setup Menus.

(2) Press the Up-arrow key to select one of the Setup Menus.
(3) Press the Mode key mois to step through the prompts.

(4) Press the Up-arrow key or the Down-arrow key to select one of the prompt values.
*Prompts may not appear, depending on controller configuration.
Figure 4.18 -
Navigating the
Output Menu.


## Output Prompts

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 $d E[1$ and Decimal 2 dE[己] parameters in the Input Menu.

## Ot 1

When you are in the Setup menus, the Series 988 displays the menu selection ( InPE, OLPE, $9 L 6 L$ or [ $\cap \cap 7$ ) in the upper display, and SEE in the lower display.

The Up-arrow or Down-arrow key selects another menu. Press the Mode key mode to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow $\boldsymbol{\square}$ and Down-arrow $\varnothing$ keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key moos.

## Output 1

Set the way that output 1 will respond to a difference between the set point and an input variable.

- HE select reverse action, so that output 1 responds when the input signal is less than the setpoint.
- $[L$ select direct action, so that output 1 responds when the input signal is more than the setpoint.

Ut 1 This prompt always appears.
Default



## Prcir Process 1

## Select the process range for output 1.

Pre 1 This prompt appears only on controllers equipped with output 1



HY5

## Hysteresis 1

Select the switching hysteresis for output 1. This determines the change in temperature or process units needed to turn the output from full on to full off.

HY5 1 This prompt does not appear on controllers equipped with output 1
 controller set up as an on/off controller ( $P \mathbf{P b} \mid \boldsymbol{R}=\square \boldsymbol{0})$.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |
| :---: | :---: |
| OF | $1 \ldots 939$ |
| $\begin{gathered} {[-\boldsymbol{F}} \\ \text { (Global Menu) } \end{gathered}$ | HY5: HY5 HY51 |
| OF \& rt.d | $0.1 \ldots 3.0$ |
| C_F in 1 <br> (Global Menu) <br> (Input Menu) | HY51 HY5 HY5: |
| ${ }^{\circ} \mathrm{C}$ | $1 \ldots 5.255$ |
| $\begin{gathered} {[-\boldsymbol{F}} \\ \text { (Global Menu) } \end{gathered}$ | HY5 HYS HYS |
| O[ \& re.d | $0.1 \ldots 2.0 .5$ |
| C_F <br> (Global Menu) in 1 <br> (Input Menu) | HY51 HY5 HYS |
|  | $1 \ldots 9393$ |
| a process input is selected | HY5: HY5 HY5 |

## Output 2

Set the way that output 2 will respond to a difference between the set point and an input variable．
－ $\operatorname{AL}$［ de－energizes output 2 in an alarm condition．
－RL己n energizes output 2 in an alarm condition．
－HE select reverse action，so that output 2 responds when the input signal is less than the set point．
－［L select direct action，so that output 2 responds when the input signal is more than the set point．
$0 \in 己$ This prompt appears only on controllers equipped with output 2
 put 2 is a process output（ $98 \ldots \ldots$＿＿F－＿＿$)$ ． HE and $\square \mathrm{L}$ do not appear if $8 L 90$（in the Global Menu）is set to $d U P L$ ．


Prce

## Process 2

## Select the process range for output 2.

Pred This prompt appears only on controllers equipped with output 2 process hardware（98＿＿－＿＿F－＿＿＿）and with Ot 己 not set to no．


## HY5

## SPCL Set Point 2 Control

## Select a second set point.

- $P_{r}$ enables a set point independent from the Set Point $1 \boxed{5 P}$ value.
- $\quad d E$ enables a set point at a deviation from the Set Point $1 \boxed{5 P}$ value.

Pred This prompt appears only if output 2 hardware is present and is equal to the output 1 setting.


ALC

## NOTE:

See Chapter 7 for more information on alarms.

## Alarm 2

Select the alarm type for alarm 2. Select the trigger points for the alarm with the R2LO and R2H i settings in the System Menu 545.

- Pr it uses the process signal from input 1. Changing the set point does not change the alarm response.
- $d E$ I uses a deviation from the input 1 signal. Changing the set point changes the alarm response.
- Pre uses the process signal from input 2. This choice does not appear if the controller is not equipped with input 2 hardware or if in $\boldsymbol{Z}$ is set to $n$ or or $E$ I.
- $\quad$ E 2 uses a deviation from the input 2 signal. This prompt does not appear if the controller is not equipped with input 2 hardware or if inट is set to no or E, 工.
-     - FLE uses the rate of change at input 1 in degrees per minute.

AL 2 This prompt appears only on controllers equipped with output 2 hardware and with $O L Z$ set to $A L D$ or $B L 己 \pi$.


## Alarm 2 Side

## Select what triggers alarm 2.

-both triggers an alarm when the signal $\leq$ ALL $O$ or $\geq$ ACH i.

- H,9H triggers an alarm when the signal $\geq$ R2H .
- LoÚ triggers an alarm when the signal $\leq$ ARLO.

A25d This prompt appears only on controllers equipped with output 2 hardware and with $O L$ ? set to $B L$ ? or $B L 2 n$.

| Default $\downarrow$ |  |  |
| :---: | :---: | :---: |
| both | H.9H | Lous |
| R25d | R25d | R25d |

## LBEC Latching 2

Select whether alarm 2 will be latching or non-latching. A latching alarm LAE must be turned off manually. A non-latching alarm nLB turns off when an alarm condition no longer exists.

LALC This prompt appears only on controllers equipped with output 2


## NOTE:

See Chapter 7 for more information on alarms.

## Silencing 2

Select silencing to inhibit alarm 2 on startup and to allow the operator to reset the alarm output, not the visual display.

- Silencing disables the alarm until the signal is between $82 L 0$ and [R2H i).

RLD This prompt appears only on controllers equipped with output 2 hardware and with OLC set to ALD or ALCn.


## Output 3

## Select the alarm condition for output 3.

－AL 3 de－energizes output 3 in an alarm condition．
－AL 3n energizes output 3 in an alarm condition．
Ot 3 This prompt appears only on controllers equipped with output 3
 98＿＿－＿＿＿＿－K＿＿＿）or switched dc（98＿＿－＿＿＿＿C＿＿」．

Default
$\downarrow$

| AL | RL3 |
| :---: | :---: |
| $0 t 3$ | $0 t 3$ |
|  | $0 \in 3$ |

## Alarm 3

## Select the alarm type for alarm 3.

－ $\operatorname{Pr}$ uses the process signal from input 1 ．
－$d E I$ uses a deviation from the input 1 signal．
－ $\operatorname{Pr}$ I uses the process signal from input 2．This prompt does not appear if the controller is not equipped with input 2 hardware or if in 2 is set to $\square$ no or $\mathcal{E}, \boldsymbol{L}$ ．
－$d E 2$ uses a deviation from the input 2 signal．This prompt does not appear if the controller is not equipped with input 2 hardware or if $\operatorname{in} 己$ is set to no or $\boldsymbol{E}, \boldsymbol{C}$ ．
－ $\operatorname{rAtE}$ uses the rate of change at input 1 in degrees per minute．
AL3 This prompt appears only on controllers equipped with output 3
 98＿＿＿＿＿＿－K＿＿）or switched dc（98＿＿－＿＿＿＿－C＿＿」，and with Ot 3 set to AL 3 or AL 3n．


## R35d <br> Alarm 3 Side

NOTE:
See Chapter 7 for more information on alarms.

## Select what triggers alarm 3.

-both triggers an alarm when the signal $\leq 8 \exists L O$ or $\geq$ R3Hi.

- $\mathrm{H}, 9 \mathrm{H}$ triggers an alarm when the signal $\geq \Omega 3 \mathrm{Hi}$.
- LOLU triggers an alarm when the signal $\leq$ R3LO.
[835d This prompt appears only on controllers equipped with output 3
 98_ _- _ _ _-K_ _ _) or switched dc (98_ _- _ _ _-C_ _ _) and with Ot 3 set to AL 3 or AL 3n.

| Default <br> $\downarrow$ |  |
| :---: | :---: | :---: |
| both   <br> B35d $\frac{H, 9 H}{\text { B35d }}$ LOLU <br> R35d   |  |

## Hysteresis 3

Select the switching hysteresis for alarm 3. This determines the change in temperature or process units needed to turn the output from off to on.

- If RL 3 is set to rAtE settings for HYS3 will be in degrees per minute or units per minute.
- If the input referenced by AL 3 is set to $r$ と.d the range is affected as listed below.

HY53 This prompt appears only on controllers equipped with output 3 hardware for a relay (98 $\qquad$ -B $\qquad$ 98 $\qquad$ -J $\qquad$ or

98_ _-_ _ _ _-K_ _ _ ) or switched dc (98_ _-_ _ _ _-C_ _ _).

| $\begin{aligned} & \text { If } \\ & \downarrow \end{aligned}$ |  | Default |
| :---: | :---: | :---: |
| ${ }^{\circ} \mathrm{F}$ |  | 3 ... 999 |
| $\begin{aligned} & \Sigma_{-} ; \\ & \text {(Global Menu) } \end{aligned}$ |  | H453 H453 HY53 |
| $\begin{gathered} \frac{\sigma F}{C-F} \\ \text { (Global Menu) } \end{gathered}$ | $\begin{aligned} & \text { \& rt.d } \\ & \text { Input 1 or 2 } \\ & \text { (see note above) } \end{aligned}$ |  |
|  |  |  |
|  |  | $\begin{array}{rrr} 0.1 & 2.0 & \cdots \\ \frac{1}{H 453} & 55.5 \\ H 453 \end{array}$ |
| a process input |  |  |

## \&Fと 3 Latching 3

Select whether alarm 3 will be latching or non-latching. A latching alarm LRE must be turned off manually. A non-latching alarm $n$ LR turns off when an alarm condition no longer exists.

LAE 3 This prompt appears only on controllers equipped with output 3 hardware for a relay (98_ $\qquad$ -B__ _, 98_ -- --J or 98___ _ _ -K_ _ ) or switched dc (98__-_ _ _-C_ _ ) and with Ot 3) set to RL3 or RL 3n.

| Default $\downarrow$ |  |
| :---: | :---: |
| n 1 ( | LAt |
| [RE3] | [RE3] |

NOTE:
See Chapter 7 for more information on alarms.

## Silencing 3

Select silencing to inhibit alarm 3 on startup and to allow the operator to reset the alarm output, not the visual display.

- Silencing disables the alarm until the signal is between 8310 and [R3HI.
[5iL3 This prompt appears only on controllers equipped with output 3
 98_ _ _ _ _-K_ _ ) or switched dc (98_ _-_ _ _-C_ _ ) and with Ot 3 ) set to RL3 or BL 3n.

Default
$\downarrow$

| OFF | On |
| :---: | :---: |
| 5123 | 5123 |

0 O4

NOTE：
See Chapter 7 for more information on alarms．

## Output 4

## Select the alarm condition for output 4.

－AL4 de－energizes output 4 in an alarm condition．
－AL4n energizes output 4 in an alarm condition．
Ot 4 This prompt appears only on controllers equipped with output 4 hardware for a relay（ 98 ＿＿－＿＿＿＿－＿B＿＿， $988_{-}$＿－＿＿＿－＿D＿$^{-}$，



Alarm 4

## Select the alarm type for alarm 4.

－ $\operatorname{Pr} 1$ uses a process signal from input 1.
－$d E I$ uses a deviation from the input 1 signal．
－ $\operatorname{Pr}$ 己 uses the process signal from input 2．This prompt does not appear if the controller is not equipped with input 2 hardware or if $\square$ ind is set to no or $\varepsilon, \mathcal{L}$ ．
－$d E 2$ uses a deviation from the input 2 signal．This prompt does not appear if the controller is not equipped with input 2 hardware or if $\operatorname{in} 己$ is set to no or $E, 己$ ．
－rAtE uses the rate of change at input 1 in degrees per minute．
RL4 This prompt appears only on controllers equipped with output 4 hardware for a relay（ 98 ＿＿－＿＿＿＿－＿B＿＿， 98 ＿＿－＿＿＿＿－＿D＿＿，


Default

$845 d$

NOTE:
See Chapter 7 for more information on alarms.

## Alarm 4 Side

## Select what triggers alarm 4.

-both triggers an alarm when the signal $\leq$ 月4L or $\geq$ 月4H .

- $H, 9 H$ triggers an alarm when the signal $\geq$ A4H .
- LOLU triggers an alarm when the signal $\leq 8420$.

845d This prompt appears only on controllers equipped with output 4 hardware for a relay ( 98 _ _-_ _ _ _-_B_ _, $988_{\__{~--}}$ _ _ _-_D_ _ ,
 and with $O E 4$ set to $\operatorname{AL} 4$ or RL4n.

```
Default
        \downarrow
    bOLH HISH LOLU
    845d [845d [845d
```


## LRE4 Latching4

Select whether alarm 4 will be latching or non-latching. A latching alarm LRE must be turned off manually. A non-latching alarm $n$ LA turns off when an alarm condition no longer exists.

LRE4 This prompt appears only on controllers equipped with output 4 hardware for a relay (98_ _-_ _ _-_B_ _, 98_ _-_ _ _ _-_J_ _ or
 to BLY or BL 4n.


## $5: 14$

NOTE:
See Chapter 7 for more information on alarms.

## Silencing 4

## Select silencing to inhibit alarm 4 on startup and to allow the operator to reset the alarm output, not the visual display.

- Silencing disables the alarm until the signal is between 8420 and [84H i.
[SiL4 This prompt appears only on controllers equipped with output 4

 and with OLY set to RLY or RL4n.



## Analog Output

Select which value to retransmit as the output 3 signal.

- Prcil retransmits the process 1 value.
- StPE retransmits the set point.

NOTE:
See Chapter 8 for more information on retransmit.

- Prcl retransmits the process 2 value. This prompt appears only if the controller is equipped with input 2 hardware and if $\square$ inc is not set to $n 0$ or $E, 2$.
- no turns off retransmit function.

Rout This prompt appears only on controllers equipped with retransmit hardware (98_ _-_ _ _-

Default
$\downarrow$

| Pret | StPt | Pras | no |
| :---: | :---: | :---: | :---: |
| Bout | [Rout | Rout | Rout |

Prc3

## Process 3

## Select the range for the retransmit signal at output 3.

Pre3 This prompt appears only on controllers equipped with retransmit hardware (98___ _ _ _-M_ _ _ or 98_ _- _ _ _- $\mathrm{N}_{\text {_ _ }}$ ) and with Rout not set to no.


NOTE:
See Chapter 8 for more information on retransmit.

## Retransmit Low Limit

## Select the low limit for the retransmit signal at output 3.

- The default value is equal to $r \mathcal{L}$ or $r \mathcal{L}$ ? (in the Input Menu) depending on whether Rout is set to Pret or Prec .
- The decimal precision of $\boldsymbol{A} r_{L}$ is determined by $d E[1$ (Input Menu) if Rout is set to Prct or StPE; it is determined by $d E[己$ ] if Rout is set to Prcl.
$\boldsymbol{A} \boldsymbol{\sim}$ This prompt appears only on controllers equipped with retransmit
 set to no.

| -999 | $A r-A$ |
| ---: | ---: |
| $A r L$ | $A r L$ |

## ArH

## BCAL

NOTE:
See Chapter 8 for more information on retransmit.

## Retransmit High Limit

Select the high limit for the retransmit signal at output 3.

- The default value is equal to $r \boldsymbol{H}$ i or $r \boldsymbol{H C}$ (in the Input Menu) depending on whether Pout is set to Pre1 or Pred.
- The decimal precision of $A[A L$ is determined by $d E[1$ (Input Menu) if Rout is set to Pre or SLPE; it is determined by $d E[$ ? if Rout is set to Prce.
$\boldsymbol{A} \boldsymbol{r H}$ This prompt appears only on controllers equipped with retransmit hardware (98_ _-_ _ _ --M_ _ or 98_ _-_ _ _ _- $\mathrm{N}_{-}$_ ) and with Rout not set to no.

$$
\begin{gathered}
A r L \\
A r H \\
\hline A r H
\end{gathered}
$$

## Retransmit Calibration Offset

Select an offset value for the retransmit signal at output 3.

- The decimal precision of $A[A L$ is determined by $d E[1$ (Input Menu) if Rout is set to Prc or StPE; it is determined by $d E[己$ if Rout is set to Prce?

A[AL This prompt appears only on controllers equipped with retransmit hardware (98__-_ _ _ _- $\mathrm{M}_{-}$_ _ or 98__-_ _ _ $-\mathrm{N}_{-}$_ ) and with Rout not set to no.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: |
| OF | -99 | 0 | 999 |
| C_F <br> (Global Menu) | ACAL | RCAL | ACAL |
| O[ | -55 |  | 555 |
| C-F (Global Menu) | ACAL | RCAL | ALAL |
|  | -99 |  | 999 |
| a process input is selected | ACAL | RCRL | ALAL |

## Reaching the Global Menu

(1) Begin in the Display Loop, and press the Up-arrow $\triangle$ and Downarrow $\square$ keys simultaneously for three seconds to reach the Setup Menus.

|  |  |  |  |
| :---: | :---: | :---: | :---: |
| inPt | OLPE | 9 CbL | [0¢7] |
| SEE | SEE | SEE | 5Et |
| Input | Output | Global | Communications |
| Menu | Menu | Menu | Menu |
| p. 4.2 | р. 4.18 | p. 4.34 | p. 4.44 |

(2) Press the Up-arrow key to select one of the Setup Menus.
(3) Press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{\Delta}$ or the Down-arrow key $\nabla$ to select one of the prompt values.

*Prompts may not appear, depending on controller configuration.

Figure 4.34 -
Navigating the
Global Menu.

## Global Prompts

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 $d E[1$ and Decimal 2 dE[己] parameters in the Input Menu.


When you are in the Setup menus, the Series 988 displays the menu selection (inPt, OLPL, $9 L b L$ or [ $\subset \cap \cap$ ) in the upper display, and SEE in the lower display.

The Up-arrow $\triangle$ or Down-arrow key selects another menu. Press the Mode key mode to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow $\triangle$ and Down-arrow $\square$ keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key moos.

## Celsius-Fahrenheit

## Select which temperature scale the controller will use.

[_F This prompt appears only on controllers with either Input 1 or Input 2 set to something other than a process input.


## Failure Mode

Select the output level that the controller will maintain if an input fails.

- Bumpless transfer bPL5 maintains the same output settings after an input failure.

FA il This prompt always appears.

| If | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: |
| $\downarrow$ |  |  |  |
| a heat/cool application | $\begin{aligned} & G P L S \\ & F R I L \end{aligned}$ | $\begin{array}{\|c} -100 \\ F R I L \end{array}$ | $\begin{aligned} & 100 \\ & F R I L \end{aligned}$ |
| a heat-only application | $\begin{aligned} & G P L S \\ & F R I L \end{aligned}$ | $\begin{array}{\|r\|} \hline F R I L \\ \hline F \end{array}$ | $\frac{100}{\text { FRIL }}$ |
| a cool-only application | $\begin{gathered} 6 P L S \\ F A I L \end{gathered}$ | $\begin{aligned} & -100 \\ & \hline F R 1 L \end{aligned}$ | $\begin{array}{r} \text { FRIL } \end{array}$ |

## $E r \boldsymbol{r} \quad$ Error Latching

## Select whether errors will be latching or non-latching.

- Non-latching alarms nLA turn off when there is no alarm condition.
- Latching alarms LAE must be turned off manually.

Err This prompt always appears.


## Entl

## Control Type

Select a control method: normal nor; cascade [SCd; ratio rAt ; or differential $d, F F$.
[ntl This prompt appears only on controllers equipped with enhanced software (98_B-_ _ _-_ _ _ ) and input 2 hardware for a basic thermocouple signal conditioner ( $988_{\__{-}} 1_{1_{-}}-{ }_{-}$) or a universal signal conditioner (98_ _-_2_ _-_ _ ) and with rSP set to OFF.


## Cascade Action

Select the control action between the inner and outer loop of a cascade system.

- Direct action dir makes the percent output from the outer loop directly proportional to the set point of the inner loop (input 2). A 100\% signal in the outer loop will set the inner loop to range high 2 rHC (Input Menu). A 0\% signal in the outer loop will set the inner loop to range low $2 r \boldsymbol{L}$ ? (Input Menu).
- Reverse action $r E D$ makes the percent output from the outer loop inversely proportional to the set point of the inner loop (input 2). A 100\% signal in the outer loop will set the inner loop to range low $2 r \mathcal{L}$ (Input Menu). A 0\% signal in the outer loop will set the inner loop to range high $2 r \mathrm{HC}$ (Input Menu).
[SAC This prompt appears only on controllers equipped with enhanced software (98_B- $\qquad$ ) and with [ntL set to [S[d.



## AL90 <br> Algorithm

## Select the control algorithm.

- $\boldsymbol{P}, \boldsymbol{d}$ selects one set of PID prompts.
- $P d r$ selects proportional/derivative control with manual reset in percent power.
- $P, d ट$ selects two complete sets of PID prompts. This selection does not appear if [ntl is set to [S[d].
- $\mathbb{U P L}$ selects duplex (heating and cooling) control. This prompt does not appear unless output 1 is a process output.

RL 90 This prompt appears only on controllers equipped with enhanced software (98_B-_ _ _ _- _ _ _ ).

Default
$\downarrow$

| P.d | Pdr | P.d己 | TUPL |
| :---: | :---: | :---: | :---: |
| 8L90 | BL90 | BLS | RLSO |

## PID 2 Crossover Selection



Select which parameter determines the crossover from PID A to PID B: process Proc; set point StPt; or none no.
[P, dट This prompt appears only on controllers with RL90 set to [P, dट].


## Proc

## SLPE Crossover Set Point Value

Select the set point value at which the control algorithm will crossover between PID A and PID B. PID A is active below this value and PID B is active above this value.

- This value cannot be set lower than range low $1 \quad r L i$ or higher than range high 1 rHi.
[StPt This prompt appears only on controllers with $P, d ट$ set to [StPt.



## E, 1 Event Input 1

## Select the effect of closing the event input 1 switch.

- no disables event input 1.
- $\angle O C$ locks out the front panel keys.
- ALr resets an alarm.
- $\boldsymbol{A - \Gamma ]}$ switches the controller to manual mode at the power level set at FA il (Global Menu) and disables the Auto/Man key.
- OFF turns all control outputs off (de-energize relays).
- $P$,d switches from PID A to PID B.
- Acta selects the opposite control action for output 1 and 2 .
- rSP switches to a remote set point.
- IdSP switches to an idle or second set point.

E, 1 This prompt always appears.


E, I

## Event Input 2

Select the effect of closing the event input $\mathbf{2}$ switch. The selections are the same as for event input 1 .
$E, \mathcal{C}$ This prompt appears only on controllers equipped with hardware for a second event input (98__-_5_ _-_ _ _ ) and with $\square$ ind set to E, ट].

Default
$\downarrow$

| no | LOL | RLr | 8-¢7 | OFF | P.d | Rctn | 1d5P |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| E, 己 | E, ट] | E, 2 | E, c | E, 2 | $E, 2$ |  | E, 2 |

## Annunciator

## Select whether alarm messages will flash in the lower display.

Rnun This prompt always appears.

Default
$\downarrow$

| On BFA BFA |
| ---: | ---: |
| Rinun |

## Low Power Limit

Select the low limit for the percent output. For cooling (direct acting) enter a negative number.

LoP This prompt always appears.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |
| :---: | :---: |
| a heat/cool application | - 100\%.. H, ${ }^{\text {H }}$ |
|  | LoP LoP |
| a heat only application | U\%... H, P |
|  | LOP LOP |
| a cool only application | -100\%.. HiP |
|  | LOP LOP |

$H, P \quad$ High Power Limit
Select the high limit for the percent output. For cooling (direct acting) enter a negative number.

H,P This prompt always appears.


RESP

## Auto-tune Set Point

Select the percentage at which the controller will auto tune the current control set point.

ALSP This prompt always appears.


## $r P$

## Ramping Function

Select when the controller will ramp. Ramping limits the speed at which an element can heat up. Ramping is often used to protect parts that would crack or warp if they heat up too quickly.

- OFF sets the system to heat as quickly as possible.
- Strt sets the system to ramp only at startup.
- StPE sets the system to ramp at startup and whenever the set point changes.
$r \boldsymbol{r}$ This prompt appears only on controllers with $r \boldsymbol{S P}$ (Input Menu) set to OFF and with $\mathcal{E}, 1$ not set to $r \boldsymbol{S P}$ and with [ntL (Global Menu) not set to d,FF or rRt $\mathbf{d}$.


FFLE Ramp Rate
Select the ramping rate in degrees per minute.
rREE This prompt appears only on controllers with $\square$ rP set to Strt or StPt.

Default $\downarrow$


## Reaching the Communications Menu

(1) Begin in the Display Loop, and press the Up-arrow $\boldsymbol{\sim}$ and Downarrow $\square$ keys simultaneously for three seconds to reach the Setup Menus.

|  |  |  |  |
| :---: | :---: | :---: | :---: |
| $\operatorname{inPt}$ | OLPE | 9 Cbl | [0¢7 |
| SEE | SEt | SEt | SEt |
| Input | Output | Global | Comm |
| Menu | Menu | Menu | Menu |
| p. 4.2 | р. 4.18 | p. 4.34 | p. 4.44 |

(2) Press the Up-arrow key to select one of the Setup Menus.
(3) Press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{\sim}$ or the Down-arrow key $\square$ to select one of the prompt values.

*Prompts may not appear, depending on controller configuration.

NOTE:


See Data Communications with the Series 988 Family of Controllers for detailed information on communications.

Figure 4.44 -
Navigating the
Communications Menu.

## Communications Prompts

When you are in the Setup menus, the Series 988 displays the menu selection ( InPE, OLPE, $9 L b L$ or [DFT) in the upper display, and SEE in the lower display.

The Up-arrow $\boldsymbol{\sim}$ or Down-arrow key selects another menu. Press the Mode key moom to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow $\boldsymbol{\square}$ and Down-arrow $\nabla$ keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key mode.

## brud

## Baud Rate

## Select the communications speed.

6FUd This prompt appears only on controllers equipped with communications hardware (98_ _-_ _ _ _-_R_ _, 98_ _-_ _ _ _-_U_ _ or 98_ _-_ _ _ __S_ _).

| Default |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 9600 | 300 | 600 | 1200 | 2400 | 4800 |
| brud | bRUd | bqud | bqud | bRUd | bRUd |

## dita

## Data Bits and Parity

Select the communications format (start bit = 1, stop bit =1).

- Setting Prot to PIod automatically sets dALA to Bn.
dAEA This prompt appears only on controllers equipped with communications hardware (98_ _-_ _ _ _-_R_ _, 98_ _-_ _ _ _-_U_ _ or 98 _ _- _ _ _ __S_ _).



## Prot Protocol Type

Select the communications protocol.

- FULL selects ANSI X3.28 2.2-A.3.
- on selects Xon/Xoff.
- CMod selects Modbus

Prot This prompt appears only on controllers equipped with communications hardware (98_ _-_ _ _ _-_R_ _, 98_ _-_ _ _ _-_U_ _ or 98 _ _-_ _ _ __S_ _).


Rddr

## Address

Select an address for the controller. The computer will use this address when communicating with this controller.

Rddr This prompt appears only on controllers equipped with communications hardware for EIA/TIA-485 and EIA/TIA-422.


## intF Interface Type

## Select the interface type for Output 4, Option S.

- 485 selects EIA/TIA-485.
- 422 selects EIA/TIA-422.
intF This prompt appears only on controllers equipped with communications hardware for EIA/TIA-485 and EIA/TIA-422 (98_ _-_ _ _ _-_S_ _).

```
Default
        \(\downarrow\)
    485422
    intF intF
```


## intF Interface Type

## Select the interface type for Output 4, Option $U$.

- 485 selects EIA/TIA-485.
- 232 selects EIA/TIA-232.
intf This prompt appears only on controllers equipped with communications hardware for EIA/TIA-485 and EIA/TIA-232 (98_ _-_ _ _ _-_U_ _).

```
Default
    \downarrow
232
    485
    intF intF
```


# Chapter 5 The Operation Menus 

## Navigating the Operation Menus

To reach the Operation Menus, begin in the Display Loop and press the Mode key moos. Depending on the controller configuration, either the Set Point 2 prompt SPD, the Idle Set Point prompt $105 P$ or the Operation Menu prompt $\triangle P E r$ will appear in the lower display. The three Operation Menus are: System 545; PID A P $P$, dA; and PID B P $P, d b$. Use the Mode key moos to step past the Set Point 2 prompt SPD or the Idle Set Point prompt IdSP, if they appear (see prompt information). Upon reaching the Operation Menu prompt OPEr use the Up-arrow or Downarrow key to select a menu and the Mode key moos to step through a menu.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 988 returns to the Operation Menu prompt OPEr. Use the Up-arrow $\square$ and Down-arrow keys to select the next menu, or use the Mode key mom to advance through the same menu again. To move backwards through the menu hold the Mode key woos down and press the Up-arrow key $\boldsymbol{\square}$. Use the Up-arrow $\boldsymbol{\square}$ or Down-arrow $\boldsymbol{\square}$ key to change the prompt setting.

(1) Begin in the Display Loop, and press the Mode key mods to reach the Set Point 2 prompt $5 P$, , the Idle Set Point prompt $\boldsymbol{1 d 5 P}$ or the Operation Menu OPEr.


Figure 5.1 -
Navigating the
Operation Menus.

(2) Use the Mode key mods to step past the Set Point 2 prompt SPI or the Idle Set Point prompt Id5P, if they appear (see prompt information). Upon reaching the Operation Menu prompt UPEr use the Up-arrow - key to select a menu.

## Reaching the System Menu


(3) Select the System Menu, then press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{\sim}$ to step through the prompt values. The Down-arrow key backs through the values.

*Prompts may not appear, depending on controller configuration.

Figure 5.2 -
The System Menu.

## System Prompts

## NOTE:

Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 dEE 1 and Decimal 2 dE[2] parameters in the Input Menu.

After you step past the Set Point 2 prompt $5 P D$ and the Idle Set Point prompt $105 P$ to the Operation menus, the Series 988 displays the menu selection (SY5, $P, d \boldsymbol{A}$ or $P, d b$ ) in the upper display and OPEr in the lower display.

The Up-arrow $\boldsymbol{\sim}$ or Down-arrow key $\boldsymbol{\sim}$ Mode key mode to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow $\triangle$ and Down-arrow $\nabla$ keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key mode.

## Set Point 2

Select a second set point that will activate output 2. This allows you to boost the heating or cooling action of the output 1 device.

- The range and default settings depend on the $\quad$ in $i, r_{i}$ and rHisettings (Input Menu).

SPD This prompt appears only if $O E 1$ and $O E C$ (Output Menu) are both set to HE or CL .

| $\angle L I$ | $\cdots$ |
| :---: | :---: |
| $5 P C$ |  |
| $5 P D$ |  |

## Idle Set Point

Select the set point to be activated by an event input. This allows you to select a temperature that will be maintained when the application is idle.

- The range and default settings depend on the $\quad$ in $1, r i t$ and rHi settings (Input Menu).

Id5P This prompt appears only if $\mathcal{E}, 1$ or $\mathcal{E}, \boldsymbol{L}$ (Global Menu) is set to 105 P .

| $r L i$ | $\cdots$ |
| :---: | :---: |
| $185 P$ |  |
| 1050 |  |

## $E \cdot 15$

## Event Input 1 Status

Indicates whether the event input 1 circuit is open or closed (read only).

E 15 This prompt appears only if E , 1 (Global Menu) is set to something other than no.

Default
$\downarrow$
OPEn CLOS
E,15 E,15

## E, 25 <br> Event Input 2 Status

Indicates whether the event input 2 circuit is open or closed (read only).

E, 25 This prompt appears only on controllers equipped with a second digital event input (98__-5__-_ _ ) and with E , ट? (Global Menu) set to something other than no.

Default
$\downarrow$
OPE CLOS
E, 25 E,25
RCLO

## Alarm 2 Low

Select the low trigger value for the output 2 alarm.
ACLD This prompt appears only if ALC (Output Menu) is set to something other than no.

| $\begin{aligned} & \text { If } \\ & \downarrow \end{aligned}$ | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: |
| lowest |  |  |  |
| Prit or Pre | value of | value of | ... A2H |
| ALC ALC | sensor | $r \mathrm{l}$ (or ric ) | A2LO |
| (Output Menu) | range | (Input Menu) |  |
| dE 1 or dEL or rALE |  | -999 | 0 |
| ALC ALC ALC |  | R2L0 | A2LO |
| (Output Menu) |  |  |  |

## Alarm 2 High

Select the high trigger value for the output 2 alarm.
ACH This prompt appears only if ALC (Output Menu) is set to something other than no.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ |  | Default |  |
| :---: | :---: | :---: | :---: |
|  | $\begin{aligned} \text { ALLD } \\ \text { ROH } \end{aligned}$ | value of <br> rHi (or rHC) (Input Menu) | highest <br> ... value of sensor range |
|  | $\begin{array}{r} 0 \\ \hline 82 H \text { i } \end{array}$ | $\begin{aligned} 999 \\ \text { R2Hi } \end{aligned}$ | $\begin{aligned} & 9999 \\ & 82 H i \end{aligned}$ |

## 8310

## Alarm 3 Low

Select the low trigger value for the output 3 alarm.
R3L 0 This prompt appears only if AL3 (Output Menu) is set to something other than no


## A3Hi <br> Alarm 3 High

Select the high trigger value for the output 3 alarm.
A3H: This prompt appears only if AL 3 (Output Menu) is set to something other than no.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{gathered} 83 L D \\ 83 H i \end{gathered}$ | value of <br> rHi (or rHC) (Input Menu) | highest <br> ... value of sensor range |
| $d E ~ i$ <br> AL 3 <br> Or <br> AL 3 <br> (Output Menu) | $\begin{array}{r} \text { rALE } \\ \text { RL } 3 \end{array}$ | $\begin{array}{r} 0 \\ \hline 83 H i \end{array}$ | $\begin{array}{r} 999 \\ \hline 83 H i \end{array}$ | $\begin{aligned} & 9999 \\ & 83 H i \end{aligned}$ |

## Alarm 4 Low

Select the low trigger value for the output 4 alarm.
R4L 0 This prompt appears only if RL4 (Output Menu) is set to something other than no.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: |
| lowest |  |  |  |
| Prit or Pre | value of ... | value of | ...84H |
| ALY AL4 | sensor | rli (or ric ) | 8420 |
| (Output Menu) | range | (Input Menu) |  |
| dE or dEc or rate |  | -999 | 0 |
| AL4 AL4 AL4 |  | 8840 | 8420 |
| (Output Menu) |  |  |  |

## F4H Alarm 4 High

## Select the high trigger value for the output 4 alarm.

R4H This prompt appears only if RL4 (Output Menu) is set to something other than no.


## Auto-tune

## Initiate an auto-tune.

$P, d b$ appears only on controllers with enhanced software (98_B-
_ _ _ _-) and with PL90 (Global Menu) set to P, id ] or CScd.

RUE This prompt always appears.

NOTE:
For more information on auto-tune see Chapter 7.

| Default $\downarrow$ |  |  |
| :---: | :---: | :---: |
| OFF | P, dA | P, db |
| RUE | RUUE | RUE |

## $L-\Gamma$ Local-remote

Select a local or remote set point. With $\square r$ selected the controller displays the remote set point rather than the internal (local) set point, and the set point cannot be changed with the Up-arrow or Down-arrow key.


## Reaching the PID Menus

(1) Begin in the Display Loop, and press the Mode key mode to reach the Set Point 2 prompt $5 P$ ], the Idle Set Point prompt $105 P$ or the System Menu 5 S5.

(2) Use Mode key mode to step past the Set Point 2 prompt $5 P$ ? and the Idle Set Point prompt idSP, if they appear (see prompt information). Upon reaching the Operation Menu prompt OPEr use the Uparrow $\triangle$ key to select a menu.
(3) Press the Mode key mods to step through the prompts.

(4) Press the Up-arrow key $\underset{\rightarrow}{ }$ to step through the prompt values. The Down-arrow key $\square$ backs through the values.

Figure 5.9 -
The PID Menus.


## PID A or PID B Prompts

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 dE[ 1 and Decimal 2 dE[2] parameters in the Input Menu.

## Pb if

 Pb ib
## NOTE:

The PID B Menu appears only on controllers with enhanced software (98_B-_-_--_-_) and with 8 h 90 set to $P, d ट$.

## Proportional Band, Output 1A or 1B

Select the proportional band for PID output 1. If set to $\boldsymbol{O}$ it functions as an on/off control, and the switching differential is determined by the HY5 1 value (Output Menu). The decimal precision is determined by dE[ I (Input Menu).

Pb IA This prompt always appears.

rE 18
rE 16

## Reset, Output 1A or 1B

Tune reset to eliminate the offset or droop between the set point and the actual process temperature for PID output 1 . When set to 0 reset is disabled.
$r E \operatorname{IA}$ This prompt appears only if $d F L$ (Calibration Menu) is set to $U 5$ and $P b$ i8 is not set to 0 .

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: |
|  |  | $\begin{aligned} 000.0 \\ \text { rEiA } \end{aligned}$ | 999.9 repeats/min. re 18 |
| $\begin{gathered} \text { Pdr } \\ \text { (Global Menu) } \end{gathered}$ | $\frac{100.0 \% \ldots}{r E!8}$ | $\frac{0.0}{r E I R} \% \ldots$ | $\frac{100.0}{-r E 18} \%$ |

it in
it ib

NOTE:
The PID B Menu appears only on controllers with enhanced software (98_B-___-____).

## Integral, Output 1A or 1B

Tune integral to eliminate the offset or droop between the set point and the actual process temperature for PID output 1. When set to 0 integral is disabled.
it IR This prompt appears only if $d F L$ (Calibration Menu) is set to 51 and $P b / 8$ is not set to 0 .

Default $\downarrow$ 0.00 ... $99.99 \mathrm{~min} . /$ repeat It 18 It 18

FRIA
rRib

Rate, Output 1A or 1B

Adjust the rate to eliminate overshoot on startup or after the set point changes. The rate setting will not influence the percent power if the process temperature is more than twice the proportional band from the set point. When set to $\quad \boldsymbol{0}$ rate is disabled.
$r A_{i A}$ This prompt appears only if $d F_{L}$ (Calibration Menu) is set to $U S$ and $P 6$ iR is set higher than 0 .

Default

0.00 ... 9.99 min.

TRIA TRIA

NOTE:
The PID B Menu
appears only on controllers with enhanced software (98_B- $\qquad$ -_-_-).

## Derivative, Output 1A or 1B

Adjust the derivative to eliminate overshoot on startup or after the set point changes. The derivative setting will not influence the percent power if the process temperature is more than twice the proportional band from the set point. When set to $\qquad$ 0 derivative is disabled.
$d E I A$ This prompt appears only if $d F L$ (Calibration Menu) is set to 51 and $P 6$ iA is set higher than 0.


## [ $\mathrm{t} \mid \mathrm{B}$

 [E16]
## Cycle Time, Output 1A or 1B

Select the time, in seconds, of a complete on/off cycle.
[Et IA This prompt appears only if in 1 (Input Menu) is not set to a process, [nti (Global Menu) is not set to [SLd and Pb if is set higher than $\quad \boldsymbol{0}$.

relay outputs

## Proportional Band, Output 2A or 2B

Select the proportional band for PID output 2. If set to $\quad 0$ it functions as an on/off control, and the switching differential is determined by the HYSZ value (Output Menu). Decimal precision is determined by the $d E[1$ or $d E[2]$ setting (Input Menu).

PbCR This prompt appears only if $\subset \cap \in L$ (Global Menu) is not set to
 (Global Menu) is set to dUPL.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ | Default $\downarrow$ |  |
| :---: | :---: | :---: |
| U5 \& OF | ( )... $25 \ldots 9999$ |  |
| $\Delta \mathcal{A}$ $\subset-\boldsymbol{F}$ <br> (Calibration Menu)  <br> (Global Menu)  | PbLR PbLR PbLR |  |
| \& $\begin{gathered}\text { Input 1 or } 2 \\ \text { (Input Menu) }\end{gathered}$ | 2.0... $25 . .999 .9$ |  |
|  | PbLR PbटR PbLR |  |
| US \& OL | 0 14.. 3999 |  |
|  | PbLR PbLA PbLA |  |
| \& | 0.0].. 14...999.9 |  |
|  | PbLR PbLR PbLR |  |
| 51 | 0.0 ... $3.0 . . .999 .9$ | \% of span |
| $d F_{L}$ <br> (Calibration Menu) | PbटR PbटR PbLR |  |

## rE2R

re己b

## Reset, Output 2A or 2B

Tune reset to eliminate the offset or droop between the set point and the actual process temperature for PID A output 2. When set to $\qquad$ reset is disabled.
rECA This prompt appears only if $d F L$ (Calibration Menu) is set to US and PbZA is set higher than $\quad \boldsymbol{O}$.

| $\begin{aligned} & \text { If } \\ & \downarrow \end{aligned}$ |  | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | 000.0 | 999.9 | repeats/min. |
|  |  | re2R | reca |  |
| Pdr | -100.0 \%... | 0.0 \%.. | 100.0 |  |
| AL 90 (Global Menu) | re2R | TECA | rech |  |

122R
it2b

NOTE:
The PID B Menu appears only on controllers with enhanced software (98_B- $\qquad$

## Integral, Output 2A or 2B

Tune integral to eliminate the offset or droop between the set point and the actual process temperature for PID output 2. When set to $\square$ integral is disabled.

ILCA This prompt appears only if $d F L$ (Calibration Menu) is set to 51 and Pb2A is set higher than $\qquad$ 0 .

|  |
| :---: | :---: |
| $\begin{array}{c}51 \\ \text { Default } \\ \downarrow\end{array}$ |
| 0.00 $\ldots$ <br> 1228 99.99 <br>  $1 t 28$ |


|  |
| :---: | :---: |
| $\begin{array}{c}51 \\ \text { Default } \\ \downarrow\end{array}$ |
| 0.00 $\ldots$ <br> 1228 99.99 <br>  $1 t 28$ |


|  |
| :---: | :---: |
| $\begin{array}{c}51 \\ \text { Default } \\ \downarrow\end{array}$ |
| 0.00 $\ldots$ <br> 1228 99.99 <br>  $1 t 28$ |


|  |
| :---: | :---: |
| $\begin{array}{c}51 \\ \text { Default } \\ \downarrow\end{array}$ |
| 0.00 $\ldots$ <br> 1228 99.99 <br>  $1 t 28$ |

FR2R
r月2b

## Rate, Output 2

Adjust the rate to eliminate overshoot on startup or after the set point changes. The rate setting will not influence the percent power if the process temperature is more than twice the proportional band from the set point. When set to $\qquad$ 0 rate is disabled.
rR2R This prompt appears only if $\quad d F L$ (Calibration Menu) is set to $U S$ and $P b C R$ is set higher than $\qquad$ 0.

Default

0.00 ... 9.93 min. raca raca

## Derivative, Output 2A or 2B

Adjust the derivative to eliminate overshoot on startup or after the set point changes. The derivative setting will not influence the percent power if the process temperature is more than twice the proportional band from the set point. When set to $\qquad$ 0 derivative is disabled.
$d E 2 A$ This prompt appears only if $d F L$ (Calibration Menu) is set to 51 and $P b ट A$ is set higher than 0

Default


NOTE:
The PID B Menu appears only on controllers with enhanced software (98_B- $\qquad$


## Operation-PID A or B

## Ct2R

 Ctटb
## db $A$

 $d b \quad b$NOTE:
The PID B Menu appears only on controllers with enhanced software (98 B- $\qquad$

## Cycle Time, Output 2A or 2B

Select the time, in seconds, of a complete on/off cycle.
[ [ $દ 2 A$ This prompt appears only if [ Cntl (Global Menu) is not set to [ [S[d and PbLR is set higher than 0 ].


## Dead Band A or B

Select the width of the zone between the action of the heating output and the cooling output. If you select a positive value the heat and cool outputs cannot be energized at the same time. If you select a negative value, both outputs can be energized at the same time.

- If a process input is selected the decimal precision will be determined by the $\quad d E[1$ setting (Input Menu).
d6 $A$ This prompt appears only if $P 62 A$ is set higher than $\qquad$ 0 and one output performs heating action and the other performs cooling action.

| $\begin{aligned} & \text { If } \\ & \downarrow \end{aligned}$ | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: |
| OF | -999 |  | 999 |
| $\begin{gathered} \boldsymbol{C}_{2} \boldsymbol{F} \\ \text { (Global Menu) } \end{gathered}$ | db 8 | db A | db 8 |
| ${ }^{\circ} \mathrm{C}$ | -555 |  | 555 |
| $\begin{gathered} {\left[\_\boldsymbol{F}\right.} \\ \text { (Global Menu) } \end{gathered}$ | db 8 | db A | db 8 |
| a process | -999 |  | 999 |
| input is selected | db 8 | db A | db 8 |

## Chapter 6 The Factory Menus

NOTE:
The Factory Menus will not appear if the hardware lockout DIP is set to on.
See Chapter 1 for more information.

NOTE:
The Factory Menus can only be entered when the setup prompt SEE is displayed.

## Navigating the Factory Menus

To reach the Factory Menus, begin in the Display Loop and press the Uparrow $\triangle$ and Down-arrow keys together and hold for three seconds. The SEE prompt will appear in the lower display. Press and hold the Up-arrow $\triangle$ and Down-arrow keys together again for three seconds until the $F_{\subset \in \mathcal{Y}}$ prompt appears in the lower display. The Factory Menus will not appear if the hardware lockout DIP is set to on. (See Chapter 1 for more information on DIP switch settings.) The three Factory Menus are: Panel Lockout PLOC; Diagnostics d, A9; and Calibration [AL. Upon reaching the Factory Menu prompt $F \subset \in \mathcal{B}$ use the Up-arrow $\triangle$ or Downarrow $\boxtimes$ key to select a menu and the Mode key mode to step through a menu.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 988 returns to the Factory Menu prompt Fct $]$. Use the Up-arrow $\triangle$ and Down-arrow $\square$ keys to select the next menu, or use the Mode key moom to advance through the same menu again. To move backwards through the menu hold down the Mode key moom and press the Up-arrow key $\boldsymbol{\sim}$. Use the Up-arrow $\boldsymbol{\sim}$ or Down-arrow $\boldsymbol{\square}$ key to change the prompt setting.

NOTE:
Press the Display
key olshan to return to the Display Loop from any point in any menu.

Navigating the Factory Menus.
Figure 6.1 -
(1) Press the Up-arrow $\triangle$ and Down-arrow $\varnothing$ keys together and hold until the SEE prompt appears in the lower display. Press and hold again until the Fcty prompt appears in the lower display.

(2) Use the Up-arrow key $\boldsymbol{\sim}$ to select one of the Factory Menus.

## Reaching the Panel

 Lockout Menu
(3) Select the Panel Lockout Menu, then press the Mode key moos to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{\triangle}$ or the Down-arrow key to select one of the prompt values.

*Prompts may not appear, depending on controller configuration.

Figure 6.2 -
The Panel Lockout
Menu.

## Panel Lockout Prompts

When you are in the Factory menus, the Series 988 displays the menu selection ( PLOL, $\boldsymbol{d , A 9}$ or [AL) in the upper display and $F \subset \in \mathcal{C}$ in the lower display.

The Up-arrow $\boldsymbol{\sim}$ or Down-arrow key selects another menu. Press the Mode key mode to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow $\triangle$ and Down-arrow $\varnothing$ keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key moob.

## Front Panel Lockout



CAUTION: Setting COC to disables the Auto/Man key $\frac{\text { RUTO }}{\text { MAN }}$ and will force the controller into manual mode if an open sensor occurs. Verify that the controller is operating in the desired mode (auto or manual) before setting the lockout level. Failure to do so could result in damage to equipment and or property.

Sets the Lockout level for the Front Panel. This allows you to disable keys on the front of the controller.

- $\quad \mathbf{O}$ enables all keys.
- 1 disables the Mode key mode.
- 2 disables the Mode key mode and the Auto/Man key $\frac{\text { AUTO }}{\text { MAN }}$.
- 3 disables the Mode key mode and the Auto/Man key $\begin{aligned} & \text { AUIO } \\ & \text { MAN }\end{aligned}$ and locks the set point value.

LOC This prompt always appears.


## Factory-Panel Lockout

The prompts within the Panel Lockout Menu allow you to lockout an entire menu. You can set the level of lockout to none nonE, read only rEAd, or lockout read and write [FULL.

545

## System Menu

Select the lockout level for the System Menu. Set the System Menu lockout to no lockout nonE, read only rERd or full lockout FULL

LOC This prompt always appears.


## P,dA

## PID A Menu

Select the lockout level for the PID A Menu. Set the PID A Menu lockout to no lockout nonE], read only rERd or full lockout FULL.
[ $P, d \boldsymbol{d}$ This prompt always appears.

| $\left.\begin{array}{l}\text { Default } \\ \downarrow \\ \\ \text { nonE } \\ \hline P, d B \\ \hline P, d B\end{array}\right]$ FULL |
| :--- |

## PID B Menu

Select the lockout level for the PID B Menu. Set the PID B Menu lockout to no lockout nonE], read only $\operatorname{rERD}$ or full lockout FULL .
$P, d b$ This prompt appears only on controllers with enhanced software (98_B-_ _ _-_ _ ) and with RL90 (Global Menu) set to P , d己 or [ntL (Global Menu) set to [S[d.


## inPt <br> Input Menu

Select the lockout level for the Input Menu. Set the Input Menu lockout to no lockout nonE, read only rERd or full lockout FU'LL.
inPt This prompt always appears.


OLPE

## Output Menu

Select the lockout level for the Output Menu. Set the Output Menu lockout to no lockout nonE], read only FERD or full lockout FULLL.

OLPE This prompt always appears.


## 9Lbi Global Menu

Select the lockout level for the Global Menu. Set the Global Menu lockout to no lockout nonE], read only $r E P d$ or full lockout $F U L L$.

9LbL This prompt always appears.


## Communications Menu

Select the lockout level for the Communications Menu. Set the
Communications Menu lockout to no lockout nonE, read only rERd or full lockout FULL.
[0円7] This prompt appears only on controllers equipped with
Communications hardware (98 $\qquad$ -_R_ or 98 $\qquad$ -_ _ _ _S_ _ ).

| Default $\downarrow$ |  |  |
| :---: | :---: | :---: |
| none | reid | FULL |
| [0\%7] | [0r7 | [0r7 |

## Diagnostics Menu

## d.89

Select the lockout level for the Diagnostics Menu. Set the Diagnostics Menu lockout to no lockout nanE, read only rERd or full lockout FULL.
d.89 This prompt always appears.

| Default <br> $\downarrow$ <br> $\downarrow$ |
| :--- |
| nonE rERD FULL <br> $d .89$ $d .89$ d.89 |

## Calibration Menu

[AL
Select the lockout level for the Calibration Menu. Set the Calibration Menu lockout to no lockout nonE, read only rERd or full lockout FULL.
[AL This prompt always appears.


## Reaching the Diagnostics Menu

(1) Press the Up-arrow $\boldsymbol{\sim}$ and Down-arrow $\square$ keys together and hold until the SEE prompt appears in the lower display. Press and hold again until the $F \subset \in \leq$ prompt appears in the lower display.

(2) Use the Up-arrow $\boldsymbol{\sim}$ key to step from the Panel Lockout Menu PLOL to the Diagnostics Menu d,89.
(3) Press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{\sim}$ or the Downarrow key to select one of the prompt values.

In the Diagnostics Menu only the values of d 15P, tout and OPLP can be changed.


Figure 6.7 -
The Diagnostics Menu.
dAtE

SOFE


## Serial Number

Shows the controller＇s serial number．The first two letters in the upper display are to indicate that the controller is in serial number mode．The right half of the upper display shows the first two digits of the serial num－ ber．The lower display shows the last four digits of the serial number．

$$
\begin{aligned}
& 5 \cap 34 \\
& 5678
\end{aligned}
$$

This is what the controller with the serial number 0988345678 would dis－ play．
［nn－－This prompt always appears．

## Ambient Temperature

Shows the ambient temperature at the Input 1 terminals．The temper－ ature is shown in ${ }^{\circ} \mathrm{F}$ in the form 000．0 regardless of the settings of $d E[], d E[己], d F L$ or $[-F$ ．

AR7b This prompt always appears．


9nd
cnt 1
cnt？


## Inputs 1 and 2 Module Types

Displays which input module is installed in the controller．Please doc－ ument this value before contacting the factory for technical assistance．

Input Types
－none No input module
－tc Thermocouple only module
－Curr Current detect
－Sl id Slidewire module
－UOOFF Universal off
－Ürtd Universal rtd
－ULeh Universal high－gain thermocouple
－UUCL Universal low－gain thermocouple
－Ur7u Universal millivolts
－uPra Universal process
－E $\boldsymbol{\varepsilon}$ I Event input 2
וヒエ1 ・ヒエス These prompts always appear．

## Factory-Diagnostics

Oty:

## Outputs 1, 2, 3 and 4 Module Types

Display the controller's output module. Please document this value before contacting the factory for technical assistance.

Output Types

- none no output module (A)
- 55 Cl 0.5A solid-state relay (K)
- 55150.5 A solid-state relay with suppression (B)
- dc switched dc open collector (C)
- $r \underline{L Y c}$ form $C$ relay (E)
- $r l \in S$ form $C$ relay with suppression (D)
- rLAb relay A/B (J)
- Proc process output (F)
- Ur $\varepsilon \in$ voltage/retransmit (N)
- $\operatorname{IrEE}$ current/retransmit (M)
- SPLY power supply (T)
- 232 EIA/TIA-232 communications (R)
- 485 EIA/TIA-485 or EIA/TIA-422 communications (S)
- 232 EIA/TIA-232 or EIA/TIA-485 communications (U)

OEY IOEYD OtY3 OLY4 These prompts always appear.

## d,5P

## tout

## Test Displays

Runs a brief test of the controller's displays and LEDs. To run the test, scroll through the Diagnostics Menu until $d, 5 P$ is shown in the lower display. Use the Up-arrow key $\triangle$ or Down-arrow key $\nabla$ to select YES from the upper display and press the mode key moob.

The controller will run pattern tests, blink all the LEDs on and off, and end with the model number in both displays.
d,5P This prompt always appears.


## Test Outputs

This prompt tests each output. To run the test, scroll through the Diagnostics Menu until tout is shown in the lower display. Use the Uparrow key $\boldsymbol{\square}$ or Down-arrow key to select an output out i, out ?, out 3] or out 4. The LED for that output should light after a second or two indicating that the output has been successfully energized. Do not press the mode key mode to activate the test; it starts automatically when anything other than OFF is selected.

If any of the LEDs fail to light contact the factory.
tout This prompt always appears.


OPLP Open Loop
Checks the control loop, consisting of the controller output, power control, heater and sensor. With open loop enabled, the controller monitors the output power level and checks for a change in the process input value. If the output power is at maximum for a period of time equal to the reset time and the process input has not changed by at least $\pm 5^{\circ} \mathrm{F}$, the controller will switch to manual mode at $0 \%$ output power and $O P L P$ will be displayed in the lower display.

To clear this error, enter the Setup Menu and press the display key olspay. To get back into auto mode, press the Auto/Man key dution

OPLP This prompt always appears.


## Reaching the Calibration Menu

(1) Begin in the Display Loop, and press the Up-arrow $\boldsymbol{\square}$ and Downarrow key simultaneously for six seconds until the Setup Menu SEE, then the Factory Menu $F \subset \in \boldsymbol{Y}$ appear.
(2) Use the Up-arrow key $\boldsymbol{\square}$ or Downarrow key to step through the Factory Menu to the Calibration Menu [AL.

(3) Press the Mode key mois to step through the prompts.

(4) Press the Up-arrow key or the Down-arrow key to select one of the prompt values.

Refer to Calibrating Watlow Process Controls for information about the Calibration Menu.

CAUTION:
Before attempting to calibrate, make sure you have the proper equipment called for in each procedure. The Series 988 is calibrated and tested before it leaves the factory. Attempting to calibrate the controller without the proper equipment could result in damage to property and/or equipment.

Figure 6.13 The Calibration Menu.

rSt

## Restore

Restores the original factory calibration values when set to पE5.
This is a simple way to recover from a mistake made while calibrating the controller.
$r$ St This prompt always appears.

| Default <br> $\downarrow$ <br>  <br> $n o$ <br> $r S t$ | $y E S$ |
| :---: | :---: |
|  |  |

$d F L$

## Default

Set the operating parameter defaults to domestic or international measures.

- US (domestic) sets the controller to ${ }^{\circ} \mathrm{F}$; rate in minutes; proportional band in degrees or units; and reset in repeats per minute.
- 5 : (international) sets the controller to ${ }^{\circ} \mathrm{C}$; derivative in minutes; proportional band in percent of span; and integral in minutes per repeat.
$d F L$ This prompt always appears.
Default
$\downarrow$
US 51
$d F L d F L$


## Chapter 7 Tuning, Manual Operation, Alarms and Error Codes

NOTE:
A useful reference on tuning is Tuning of Industrial Control Systems by Armando B. Corripio, published by the Instrument Society of America.

NOTE:
Auto-tune can be initiated if rSP is set to $\qquad$ on.

NOTE:
For information about tuning a cascade system, see Chapter 9.

## NOTE:

Before attempting to auto-tune a cascade system, see Cascade Setup in Chapter 9.

Figure 7.1 -Auto-tuning example.

## Auto-tuning (Heat and/or Cool)

The Series 988 can automatically tune the PID parameters to fit the characteristics of your particular thermal system.

Standard software units (98_ $\mathbf{A}$ - $\qquad$ ) have 1 set of PID parameters. Units with enhanced software (98_ B -_ _ _-_ _ _ ) and RL90 set to $P, d 己$ (Global Menu) have two sets of PID parameters, PID A and PID B. Only one PID set can be auto-tuned at a time. For information on tuning a cascade system, see Chapter 8.

Before beginning the auto-tune sequence, make sure the RLSP parameter located in the Global Menu is at the proper setting. This allows the user to select the tuning set point as a percentage of the current control set point. See Chapter 4 for more information on this parameter. The figure below uses the default setting, $90 \%$, to define the auto-tuning process.

Once the auto-tune sequence has begun, the output 1 and output 2 proportional band is set to 0 and the control goes into an on/off mode of control at the set point percentage determined by the $\operatorname{HE} 5 P$ parameter. The displayed set point remains unchanged.

Auto-tuning at a set point of $200^{\circ} \mathrm{F}$



CAUTION:
If a mechanical relay or contactor is switching power to the load, a longer cycle time may be desirable to minimize wear on the mechanical components. The typical life of a mechanical relay is 100,000 cycles. Verify that the cycle time selected is appropriate for the output device type. Failure to do so could result in damage to equipment and/or property.

When the control finishes "learning" the system, it resumes standard PID control using the PID values established by the auto-tuning process. Changing the set point during an auto-tune restarts the auto-tune procedure.

During auto-tuning the process must cross the set point four times within an 80-minute time span for the Series 988 to successfully complete the auto-tune. If this does not happen within the 80-minute time limit, the Series 988 chooses PID values based on the 80 -minute tuning cycle performed.

## To start auto-tuning:

1. Press the Mode key moob to advance to the System Menu 545. Press the Mode key moos to advance through the menu until the Ru't prompt appears in the lower display.
2. Use the Up-arrow $\triangle$ or Down-arrow $\nabla$ key to select $P, d A$ or $P, d b$,
 Only one PID set can be auto-tuned at a time.
3. Press the Display key IssLay. While the control is in the tuning mode the lower display alternates every second between the normal information and the tunE prompt.
4. When tuning is complete, the displays return to their previous state and FULE reverts to OFF. The Series 988 installs the PID tuning parameters it has calculated and saves them in non-volatile memory.

To abort auto-tuning either reset the RU'E prompt to off, press the Auto/Man key auto twice, or cycle power off and on. In all cases, aborting auto-tune restores all values to their state before auto-tuning began.

## Manual Tuning

For optimum control performance, tune the Series 988 to your thermal system. The tuning settings here are for a broad spectrum of applications; your system may have somewhat different requirements. NOTE: This is a slow procedure that may take hours to obtain optimum values.

Tune heating outputs at a set point above the ambient process value. Tune cooling outputs at a set point below the ambient process value.

If your controller is equipped with enhanced software (98_B-_ _ __ $)$, the $P, d b$ parameters may need to be tuned also. Perform this procedure on both PID sets, they are functionally identical. The parameters within the procedure apply to both output 1 and 2, and PID A and $B$.

1. Apply power to the Series 988 and enter a set point. Begin with
 set to OFF.
2. Proportional Band Adjustment: Gradually increase $P_{b}$ until the upper display process value stabilizes at a constant value. The process value will not be right on set point because the initial reset value is 0.00 repeats per minute. (If $\square \mathrm{Pb}$ is set to $\quad 0$ then $r \boldsymbol{r}$, IE, rA and $d E$ are inoperative, and the Series 988 functions as a simple on/off control.) The HYS prompt determines the switching differential value.
3. Reset/Integral Adjustment: Gradually increase $r \mathcal{E}$ or it until the upper display process value begins to oscillate or "hunt." Then slowly decrease $r \boldsymbol{E}$ or it until the upper display stabilizes again near set point.
4. Cycle Time Adjustment: Set $\square[\varepsilon$ as required. Faster cycle times sometimes achieve the best system control. See Chapter 8 for more information on the burst fire feature. However, if a mechanical contactor or solenoid is switching power to the load, a longer cycle time may be desirable to minimize wear on the mechanical components. Experiment until the cycle time is consistent with the quality of control you want. [t will not appear on units with a process output (98_ _ -_ _ F _-_ _ _ or 98 _ _ _ _ _ $\mathrm{F}^{-}$- _ _ _ ).
5. Rate/Derivative Adjustment: Increase $\quad \boldsymbol{r A}$ or $\quad d E$ to 0.10 minute. Then raise set point by $20^{\circ}$ to $30^{\circ} \mathrm{F}$, or $11^{\circ}$ to $17^{\circ} \mathrm{C}$. Observe the system's approach to the set point. If the load process value overshoots the set point, increase $\square \boldsymbol{r A}$ or $\quad d E$ to 0.50 minutes.

Raise the set point by $20^{\circ}$ to $30^{\circ} \mathrm{F}$, or $11^{\circ}$ to $17^{\circ} \mathrm{C}$ and watch the approach to the new set point. If you increase $\square \boldsymbol{\rho Q}$ or $\square \boldsymbol{d E}$ too much, the approach to set point will be very sluggish. Repeat as necessary until the system rises to the new set point without overshooting or approaching the set point too slowly.
6. Calibration Offset Adjustment: You may want your system to control to a process value other than the value coming from the input sensor. If so, measure the difference between that process value (perhaps at another point in the system) and the process value showing in the upper display. Then enter the $[8 L$ offset value you want. Calibration offset adds or subtracts degrees from the value of the input signal.

NOTE:
When a sensor opens, the controller switches from automatic to manual operation.

## Manual and Automatic Operation

To change from auto to manual operation, press the Auto/Man key $\frac{\text { Rul }}{\omega \mathrm{D}}$ twice.

Manual operation provides open-loop control of the outputs from a range of $-100 \%$ to $100 \%$ output. The Series 988 allows a negative output value only when $O \mathbb{O L}$ or $\square$ I (Output Menu) is set to $[1$ (cool).
Automatic operation provides closed-loop on/off or PID control. When the operator transfers from a closed loop to an open loop, the Series 988 sets the power level to the setting of the $F A$ IL parameter. If $F A$ il is set to $6 P L 5$ the controller retains the power level from the closed-loop control. When the Series 988 returns to closed-loop control, it restores the previous set-point process value.

The Auto/Man LED (located on the Auto/Man key $\frac{\mathrm{RODO}}{\mathrm{WWN}}$ ) indicates whether the controller is in automatic or manual operation. When the LED is lit, the control is in manual operation. When the LED is off, it is in automatic operation. When the LED flashes, press the key again within five seconds to complete the change in operation.

- If $F A$ il is set to $6 P L 5$ and the process has stabilized at a power level less than $75 \%$ ( $\pm 5 \%$ ) for a two-minute period prior to the sensor break, then the Series 988 switches to manual operation at the last automatic power level. If these conditions are not met, the output goes to $0 \%$ power (output disabled).

When transferring from automatic to manual operation, the control output, or outputs, remain stable - a bumpless, or smooth, transition. The lower display changes from the set point to the \% output value.

- If $F A$ IL is set from 100 to 100 , the Series 988 switches to manual operation at that percent power.


## Changing the Output 3 Alarm Jumper

If you have model number $\underline{98}$ _ _-_ _ _- $\underline{\mathbf{J}}_{\text {_ _ }}$, output 3 can be configured as a Form A (NO and common contact) or Form B (NC and common contact) alarm. To change the alarm jumper:

1. Remove the control from the case. Release the two tabs on one side of the control, then release the two tabs on the opposite side. You may need to rock the bezel back and forth several times to release the chassis.
2. Set the jumper to the position you want. See below for jumper location.

Figure 7.5 Alarm jumper location.

3. Return the controller chassis to the case. Be sure you have it oriented correctly. Press firmly, but gently, to seat the chassis.

If you select Form A, the contact is open when power is removed from the control. If you select Form B, the contact closes when power is removed.

NOTE:
An alarm display will be masked by an error condition or when the control is in the Calibration or Setup menus.

## Using Alarms

Output 2, 3, and 4 of the Series 988 can function as alarms. This is
 ALC, $B L 3$ or $B L 4$ is selected, the output is energized in the nonalarm condition and de-energizes the output in the alarm condition. Selecting $A L 2 \pi, A L \exists n$ or $A L 4 \pi$ reverses this action: de-energizing the output in a non-alarm condition and energizing it in an alarm condition.

If the L2, L3 or L4 LED on the front panel is lit, this indicates an alarm condition for output 2,3 or 4 respectively.

Once you've configured the outputs as alarms, enter the Output Menu again and select the $B L 2, ~ B L 3$ or $A L 4$ prompt. At these prompts you can select the type of alarm: process; deviation; or rate. Each may be independently set low and high. Choose between Prid (process alarm input 1), $\operatorname{Pr} \boldsymbol{C}$ (process alarm input 2), $d E 1$ (deviation alarm input 1), $d E D$ (deviation alarm input 2) or $r A E E$ (rate alarm referenced to input 1).

Example: $\operatorname{Pr}_{\mathrm{r}}$ can reference the input 1 process value against the $A \mathcal{A L D}$ and $A Z H$ settings, or $\operatorname{PrD}$ can reference the input 2 process value against the $A C L D$ and $A 2 H$ settings.

A process alarm sets an absolute temperature range or process value range. When the temperature or process leaves the range an alarm occurs. A process alarm is not tied to the set point.

Example: If your set point is $100^{\circ} \mathrm{F}$ and a process alarm high limit is set to $150^{\circ} \mathrm{F}$ and the low limit is set to $50^{\circ} \mathrm{F}$, the high limit trips at $150^{\circ} \mathrm{F}$, and the low alarm at $50^{\circ} \mathrm{F}$. If you change the set point, the process alarm limits remain the same.

A deviation alarm alerts the operator when the process strays too far from the set point. The operator can enter independent high and low alarm settings. The reference for the deviation alarm is the set point. Any change in set point causes a corresponding shift in the deviation alarm. Low alarms are usually set at a negative deviation while high alarms are a positive deviation.

Example: If your set point is $100^{\circ} \mathrm{F}$, a deviation alarm high limit is set to $+7^{\circ} \mathrm{F}$ and the low limit is set to $-5^{\circ} \mathrm{F}$, then the high alarm trips at $107^{\circ} \mathrm{F}$, and the low alarm at $95^{\circ} \mathrm{F}$. If you change the set point to $130^{\circ} \mathrm{F}$, the alarms follow the set point and trip at $137^{\circ} \mathrm{F}$ and $125^{\circ} \mathrm{F}$.

A rate alarm alerts the operator when the process monitored by input 1 is increasing at a rate higher than the alarm high setting ( ACH ), AJHi or A4H i ) or decreasing at a rate lower than the alarm alarm low setting ( $A \mathcal{L} O, A 3 L D$ or $A Y L D$ ). The rate is sampled once a second.

Alarms can be latching or non-latching. When the alarm condition is removed, a non-latching alarm automatically clears the alarm output and alarm message, if one is present. You must manually clear a latching alarm before it will disappear.

The alarm output is indicated by the corresponding LED on the front panel: L2; L3; or L4. There may be an alarm message flashing in the lower display, but if the Anun prompt is set to BFF (Global Menu), no alarm message is displayed. When an alarm message is displayed, it alternately flashes with the current prompt at a one-second interval in the lower display.

To clear a latching alarm, first correct the condition then press the Auto/Man key $\frac{\text { Auro }}{\text { Wan }}$ once.

Alarm silencing is available with all alarms. This function overrides the alarm on initial power up. On power up, the alarm message will not appear and the appropriate L2, L3 or L4 LED and output will reflect a non-alarm condition. Silencing is active until the process has entered the safe region located between the low- and high-alarm settings. Then deviation outside this safe zone triggers an alarm. If an alarm occurs at this point, the output can be silenced by pressing the Auto/Man key AUTO once, but the controller still displays the alarm message.

## Error Code E1 and E2 Messages

Four dashes, $-\cdots$, in the upper display indicate a Series 988 error. The control goes into the manual mode and maintains the percent output selected at the $F$ R iL prompt (Global Menu). That value (percent of output) is shown in the lower display.

## E I I EC 1: A/D underflow error

The analog-to-digital (A/D) converter of the input indicated by the first number is under range. An open or reversed polarity sensor is the most likely cause. Check the sensor. Make sure the input prompt is set to the correct sensor.


## E 1 2] E己 2: Sensor under-range error

The sensor at the input indicated by the first number generated a value lower than that allowed for the range of the sensor, or the analog-to-digital (A/D) converter malfunctioned. Make sure the setting for the input (Input Menu) matches the sensor type and that the sensor range falls within the range of the process being controlled.

## E 13 [ C 3): Sensor over-range error

The sensor at the input indicated by the first number generated a value higher than that allowed for the range of the sensor, or the analog-to-digital (A/D) converter malfunctioned. Make sure the setting for the input (Input Menu) matches the sensor type and that the sensor range falls within the range of the process being controlled.

## E : 4 E C 4: A/D overflow error

The analog-to-digital (A/D) converter at the input indicated by the first number is over range. An open or reversed polarity sensor is the most likely cause. Check the sensor. Make sure the input (Input Menu) is set to the correct sensor type.

The analog-to-digital (A/D) converter input voltage may be too high to convert an A/D signal.

## $\operatorname{Er}$ 3: Ambient temperature error

The ambient temperature of the Series 988 has dropped below $32^{\circ} \mathrm{F} / 0^{\circ} \mathrm{C}$ or risen above $149^{\circ} \mathrm{F} / 65^{\circ} \mathrm{C}$. Calibration errors can also cause this error code. Try setting rSE (Calibration Menu) to $Y E S$ ). (Read about Factory Calibration in Chapter 6.)

Er 4: RAM verification error
An internal RAM failure has occurred. Contact the factory.

## $\varepsilon r$ S: Non-volatile checksum error

An EEPROM checksum error was detected. Turn the power off then back on again. If this does not clear the error, contact the factory.

## OPLP: Open-loop detect

This error is not available while in the on/off mode. It is only active when $O P L P$ is set to on (Diagnostics Menu).

## Er 9: Configuration error

An incorrect module has been installed in the control. Contact the factory.

## Error Code Actions

## All of the above error codes except $\square \varepsilon_{r} 4, \square \varepsilon_{r} 5$ and $\varepsilon_{r} 9$ will result in these conditions:

- If FA il is set to $6 P L S$ (Global Menu)...
...and the control was in automatic operation when the error occurred, it goes into manual (\% power) operation. If the output power is less than $75 \%( \pm 5 \%)$ power and there was a change in power ( $<5 \%$ ) within the last two minutes, the Series 988 switches to manual operation at the last automatic power level (bumpless transfer). If the control was in manual operation, it remains there. (Press the Auto/Man key upper display for five seconds and the lower display shows the \% power. After five seconds the upper display reverts to the $-\cdots$ display.
- If the control was operating with stable output values when the error occurred, it continues to operate at those levels on a percent-power basis.
- If output values were not stable, or the percent output was greater than $75 \%$, the control outputs drop to $0 \%$ power (off).
- If FR IL is not set to bPLS...
$\ldots$ and the control was in automatic operation when the error occurred, it goes into manual (\% power) operation. The power level is determined by the $F 8$ il prompt value $(100$ to $\square 100$ percent).

NOTE:
An alarm display will be masked by an error condition or when the control is in the Calibration or Setup menus.

## To clear an error code...

- If Err is set to $n \mathcal{L}$, the error code should clear once the problem is corrected.
- If Err is set to LAE, correct the problem and cycle power. You can also clear the error by pressing both the Up-arrow $\triangle$ and Downarrow $\nabla$ keys to enter the Setup Menu, then press the Display key IISLLAN.


## Error codes $\varepsilon_{r} 4, \varepsilon_{r}$ S and $\varepsilon_{r}$ G will result in these conditions:

- The control is in automatic operation with both control outputs off.
- The alarm outputs are in their alarm state (de-energized with the LED lit).
- The lower display is blank.
- The upper display indicates the error code.
- All keys are inactive.
- With ErS, all Setup Menu prompts return to default values.
- The above conditions occur regardless of the FA il value, or the settings in the Setup and Factory menus.

Cycle power to the control. If the error is still present contact the factory.

# Chapter 8 General Software 

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## Burst Fire

## Requirements

- This feature only works with zero-cross, solid-state devices. It will not function correctly with random-fire devices.
- To enable burst fire the Series 988 must have an open collector or solidstate relay output: controllers with option "B," "C" or "K" selected for
 _-_ _ _ _-*_ _ 」) or output 4 ( 98 _ _-_ _ _ _-_*- _).
- The time burst is appropriate for fast loads or very tight control. It provides advantages only for PID control, not for on/off control.
- The short time bases used by burst fire makes it incompatible with the
 requires a minimum of 300 milliseconds on time to get a reading.
- The Series 988 has built in zero-cross detection circuitry, eliminating the need for external firing circuitry to trigger SCR's. The controller will not allow burst fire to be selected if its zero-cross detection circuitry is not functioning.
- The feature is enabled by selecting burst fire brSt at the cycle time


- Only the 988 and 989 can use the burst fire feature. The low-voltage units ( 986 and 987) cannot use burst firing.


## Overview

Variable, time-base burst firing from the Series 988 provides the most even distribution of power with the lowest level of noise generation (RFI). An SSR or SCR firing card translates a command signal into a burst of ac cycles. The output is zero-cross fired, which always allows at least one full ac cycle to pass within the variable time base. Burst firing is the preferred mode to control resistive loads.

The Series 988 detects when the ac sine wave of the load will cross the 0volt point. It uses this information to switch the load on or off only at a 0 volt point, minimizing RFI.

The burst fire time base in the Series 988 varies from a maximum 1.66second time base ( 1 -percent output; 1 cycle on, 99 off) down to a 33.3 -millisecond time base (50-percent output; 1 cycle on, 1 off). The graphs on the next page show how the time base varies with the percent output.


Figure 8.3a-Sine waves of burst fire settings.


Figure 8.3b -

## Semiconductor

 oven with burst fire.
## Sample Application

A Series 988 controls a heated platen in a semiconductor oven. Previously it used a power control requiring a $4-20 \mathrm{~mA}$ signal to implement burst-fire control. We have replaced the power control with a Watlow Loyola QPAC with a GCD card that accepts a signal directly from an open-collector output of the Series 988 . This gives smooth control at a lower overall system cost.

## Communications

## Requirements

Choose which interface your application will use: EIA/TIA-232 serial communications (98_ _ _ _ _-_R_ _), EIA/TIA-485 or EIA/TIA 232 serial communications (98___ _ _-_U_ _) or EIA/TIA-485 or EIA/TIA-422 serial
 ble serial port or an appropriate converter must be used.

## Overview

The serial communications feature allows the Series 988 family to receive commands from and transmit data to a master device, usually a computer. Any function that can be performed via the front panel, can also be accomplished using a serial communications port, allowing you to operate the controller from a computer and to store process data on a computer. L4 acts as the RX/TX indicator on the front display panel of the 988.

The Series 988 is available with a choice of serial hardware interfaces. An EIA/TIA-232 interface allows for one master (computer) and one controller, with a maximum network length of 50 feet ( 15 meters).

The EIA/TIA-485 or EIA/TIA-422 option equips the controller for a multidrop interface: up to 32 total network devices with EIA/TIA-485 and up to 10 total network devices with EIA/TIA-422. Each controller will have its own unique address. The total maximum network length is 4,000 feet (1,219 meters). All interfaces are isolated.

To select between EIA/TIA-485 or EIA/TIA-422, enter the Setup Menus by holding the up-arrow and down-arrow keys simultaneously until setup $5 E E$ appears in the bottom display. Use the up-arrow key to select the Communications Menu [OCT]. At the interface prompt int select between 422 or 485.

Other parameters that must be configured in the Communications Menu [ $[0 \Gamma 7$ ] are the baud rate bRUd, data bits and parity dRtB], protocol [Prot, and device address Rddr. The protocol prompt must be set to full (ANSI X3.28 2.2-A3) or RTU Modbus if multiple devices are used with the EIA/TIA-485 or EIA/TIA-422 interface. If the full protocol or RTU Modbus is selected, a device address must be selected at the address prompt. For EIA/TIA-232, full FULL or on $\square$ on (XON/XOFF) protocol may be selected.

## General Software



Figure 8.5 - Test chambers with communications.

## Sample Application

A test engineer uses Series 988 s to control the temperatures of several automated test chambers. His computer is linked to the controllers through its EIA/TIA-422 serial communications port. His computer program monitors the temperatures of the chambers and initiates automatic test sequences when certain program parameters are met. After completing a sequence, the computer loads the next temperature to the controller. The computer periodically interrogates each controller for its process temperature, set point and alarm status. This information is stored on a disk to provide test verification data for the completed products.

## Dead Band



WARNING:
If the dead band is set to a negative value, the heat and cool outputs can both be ON at the same time.

## Requirements

The dead band feature is standard on any Series 988 controller with two control outputs. The dead band prompts will appear if the control outputs are configured for heat/cool or cool/heat.

## Overview

The dead band prompts, $d \boldsymbol{d} \boldsymbol{\beta}$ and $\mathbf{d b} \boldsymbol{b}$, located in the PID menus, determine the amount of interaction between heat (reverse acting) and cool (direct acting) control outputs. The dead band directly offsets the target set point of the cool control output.

With a positive dead band, both control outputs will never be ON at the same time. With the process in a positive dead band, the output value is determined by adding the percent heat output to the percent cool output and only applying the result to the correct output - cooling action if the sum is negative and heating action if it is positive.

Figure 8.7a Dead band graph.


Figure 8.7b -
Environmental chamber with dead band.

## Sample Application

An engineer for an environmental chamber manufacturer, who is designing the heating and cooling system for a new chamber, wants to minimize the energy costs of operating the chamber. She has chosen the Series 988 and will configure the heat and cool outputs with a positive dead band.

When the chamber temperature is near ambient the cooling and heating systems had a tendency to buck one another, resulting in inefficient use of energy. The engineer started with a dead band of five degrees, but in the process of tuning the system for optimal control, the setting was reduced to two degrees. This made the chamber more energy efficient and reduced wear on the refrigeration system.

## Digital Events

## Requirements

A single digital event input is standard on all controls. A second digital


## Overview

The digital event input options on the Series 988 controller allow the operator to select one of several software functions with the close of a cus-tomer-supplied switch or by a change in dc voltage (See Chapter 2 for voltage and wiring information.).

The list below outlines the functions that can be controlled with a digital event input:

- Idle set point $1 d 5 P$ lets the operator select a second (idle) set point.
- Turn control outputs off $\square$ OFF inhibits the control outputs.
- Alarm reset RLr resets alarms from a remote location.
- Switch PID sets $\quad$ P , d selects between PID set A or B (requires enhanced software, 98_B-_ _ _ _- _ _ 」.
- Remote set point rSP switches to remote set points.
- Front panel lockout $\angle D \subset$ locks out the front panel keys to prevent tampering.
- Control output action Rctn switches the control action of outputs 1 and 2 from heating to cooling, or vice versa.
- Auto/Manual operation $\boldsymbol{R - \Gamma 7}$ switches to the manual mode of operation at the percent power selected with FR iL (Global Menu) and disables the Auto/Man key.


## General Software



Figure 8.9 - Heater with digital event.

## Sample Application

A manufacturing engineer is building an application that needs to switch to an idle temperature at the end of a batch and maintain that temperature until the next batch is loaded, with minimum operator interaction.

By connecting an external switch to the digital event input, he can select either the operating temperature or the idle temperature with the flip of a switch. The idle set point prompt is enabled by setting the Event Input 1 prompt E , i, in the Global Menu, to idle set point IdSP. The idle set point value is accessed by pressing the MODE key moos from anywhere in the display loop. When the switch closes, the lower display will indicate the idle set point, and the controller will maintain this new set point.

## NOTE:

To obtain a reading, the output ON-time must be a minimum of 0.3 seconds.

NOTE:
The heater current feature will not function with burstfire outputs.

## NOTE:

The heater current feature will not function when the Series 988 has a process output for output 1.

## Heater Current

## Requirements

Choose the heater current option (98_ _-_4_ _-_ _ _ ) for input 2 and an appropriate current transformer. A current transformer must be ordered separately.

Output 1 cannot be used as a process output. The heater current feature monitors only output 1.

## Overview

The heater current feature measures and responds to heater current in a system. This is an ideal method for detecting heater loss in applications with multiple heaters. The current is measured when output 1 is on. For instance, if a system has five, 10 -amp heaters, the heater current input measures 50 amps regardless of the percent output.

To view the heater current press the DISPLAY key and advance to the Process 2 prompt $\operatorname{Pr} \quad$ 2. The upper display indicates the last valid current reading.

The Input 2 prompt in己 under the Input Menu inPt can be set to current [urr or loop error detect LooP. Current [urr allows you to monitor heater current and set alarm set points based on high and low heater current values. Alarms can only be configured as process alarms (see Alarms, in Chapter 7). Setting to loop error detect LooP enables monitoring and alarm functions, and also triggers an error and shuts off all outputs if current is present with output 1 off or when no current is present and output 1 power is more than zero.

There are limits associated with this feature:

- To obtain a reading, the output on-time must be a minimum of $0.3 \mathrm{sec}-$ onds. To calculate this, multiply the percent output by the cycle time setting. Example: With 30 -percent output and a 2.0 second cycle time, the on-time would be: $0.30 \times 2.0=0.6$ seconds. This would yield a valid reading. If a valid reading is not possible, the 988 will display the last valid reading.
- The heater current feature will not function with burst-fire outputs: Controllers with option "B," "C" or "K" selected for output 1

 sarily apply to the loop error detect feature. If enabled, any current detected with no output triggers an error.
- This feature will not function when the Series 988 has a process output
 the current. There is no cycle time associated with process outputs.

The maximum signal the input can accept from the current transformer secondary is 50 mA . So, you must calculate the output range of the current transformer before wiring the system.


Figure 8.11 Compression molding press using the heater current feature.

## Sample Application

The Series 988 controls the lower platen of a compression molding press that contains five, 10 -ampere heaters. A 50A:50mA current transformer is used to monitor heater current.

Set the Input 2 prompt $\operatorname{inc}$ ] to current [urr , the Range Low 2 prompt $r \mathcal{L}$ to 0 and the Range High 2 prompt $r \boldsymbol{H C}$ to 50 . Find the range high 2 value with the following equation:
range high $2=\ldots($ maximum CT primary current (load current) $) \times 50 \mathrm{~mA}$ (maximum output from CT secondary (input))

The application uses a Watlow current transformer (CT) part\# 16-0233, which has a maximum input of 50 amperes, which corresponds to a maximum output of 50 mA .

$$
\text { range high } 2=\frac{(50 \mathrm{Amps})}{50 \mathrm{~mA}} \times 50 \mathrm{~mA}
$$

Solving for rH2 gives you 50. This is the range high 2 setting.

## Input Filter

## Requirements

This feature is standard on all Series 988 controllers.

## Overview

In certain applications the process being measured can be unstable, which makes it difficult to control and also makes the constantly changing display difficult to read. The Series 988 input filter can solve these problems by smoothing out just the display or the display and the input signal.

You can set a time constant in seconds for a low-pass filter that will, if you select a positive value, affect the display only. Select a negative value to filter the input signal itself.



Figure 8.13a -
Display readings with input filtering.


Figure 8.13b Humidity chamber with input filtering.

## Sample Application

A Series 988 controls the humidity in an environmental chamber. The relative humidity ( RH ) sensor provides a $4-20 \mathrm{~mA}$ signal over a $0-100 \% \mathrm{RH}$ range. The sensor is very sensitive to changes caused by air flow in the chamber. The turbulence in the chamber makes the controller display jump two to three percent. To remove this display dithering set the filter time constant Fとr 1 for input 1 to two seconds. This will smooth the display and provide a more realistic reading.

## Input Linearization

## Requirements

The square root extraction feature is standard on any Series 988 controller with universal signal conditioner inputs. The linearization prompt will appear if a process input is selected with the DIP switches (see Chapter 1).

## Overview

In many flow applications the output signal from a flow transmitter represents a squared value of the actual flow. The square root must be extracted from the signal to make it useful to the operator. Many flow transmitters offer this feature in the transmitter itself, but this can add significantly to the cost. Using the square root extraction option in the Series 988 controller can save the operator money. The feature is enabled simply by setting input 1 linearization $L$ in $i$ or input 2 linearization $L$ inc to square root extraction root.

Figure 8.15a -
Graph of linearized signal.

Figure 8.15b -
Waste-water treatment with input linearization.



## Sample Application

A waste water process engineer needs to control the flow of a solution to be mixed with wastewater to treat it. The transmitter provides a $4-20 \mathrm{~mA}$ output without square root extraction. The engineer used the Series 988 with a universal signal conditioner input and a $4-20 \mathrm{~mA}$ process output to control the flow. The input signal was linearized using the square root extraction feature of the 988.

The above system has a flow range of 0 to 16 gallons per minute. The range low and range high parameters for input 1 would be set to 0 and 16 respectively. The input 1 linearization prompt $L$ in $i$ would then be set to square root extraction root. You can see from the above graph that without square root extraction to linearize the signal it would not be useful for controlling the process.

## Ramp To Set Point

## Requirements

This feature is standard on all units.

## Overview

Ramp to set point enables the Series 988 to ramp the set point at a userdefined rate. This allows the controller to start up a system or change between set points at a rate that will not stress the product or system components. The ramp rate is defined in degrees per minute. Ramp to set point can be initiated at start up only, or at start up and also on any set point changes.

When a ramp is initiated, the starting point for the ramp is the current process value. If the ramp is initiated on start up, the Series 988 looks at the process value upon power up, and uses that value as the starting point for the ramp. If a set point change initiates the ramp to set point function, the controller looks at the process value when the change is made and uses that value as the starting point for the ramp. If the set point is changed during a ramp, the process value at the time of the change becomes the starting point for the new ramp.

## General Software



Figure 8.17 -
Muffle furnace with ramp to set point.

## Sample Application

An engineer needs to control the temperature of a muffle furnace. The furnace set point must be ramped up at a defined rate to prevent stressing the muffle and other system components. By enabling the ramp to set point function in the Series 988, the engineer can control the rate at which the set point will rise. Ramp to set point is enabled in the Global Menu using the Ramping Function prompt $r \boldsymbol{r}$. To ramp on start up only, select start $5 \ell r \boldsymbol{t}$. To ramp on start up and on any set point changes, select set point $5 \angle P E$. The ramp rate $r$ RLE is in degrees per minute.

For further protection of the system, output 2,3 or 4 can be configured as a rate alarm, monitoring the rate of increase or decrease in the process variable on input 1. The Alarm Low $A \mathcal{A L D}$ and Alarm High AZH i prompts (The "2" in these examples refers to output 2.) establish the ramp-down and ramp-up rate set points, respectively, in degrees per minute.

## Remote Set Point

## Requirements

 signal conditioner (98_ _-_2_ _- _ _ _ ).

To use a Series 988 as a master controller, choose one of the retransmit
 20 mA ; or $98{ }_{\text {_ _ _ _ _ _- }}$

## Overview

NOTE:
Input 1 and 2 are not isolated from each other.

The remote set point feature allows the Series 988 to use a thermocouple, RTD or process signal at input 2 to establish the set point. This feature gives the Series 988 the ability to have its set point value manipulated by an external source. A common application would use one ramping controller with a set-point retransmit output to ramp multiple controllers using the remote set point. Or you could use an analog output from a PLC to send set point values to a Series 988 .

You may select between local and remote set points at the front panel, with an event input, from a remote computer using the communicatons feature or from an external switch using an event input.


Figure 8.19 Zone heating with remote set point.

## Sample Application

An engineer has a machine with eight independent zones of heat. He wants to change set points on all zones without having to adjust each control individually. This can be achieved using a Series 988 with a $0-5 \mathrm{~V}=$ (dc) retransmit output as the master controller. The seven remote 988 s will use the $0-5 \mathrm{~V}=$ (dc) signal on input 2 as a remote set point. When the set point is changed on the master controller, the retransmit output changes the set points of the seven remote controllers. By enabling the ramp to set point feature in the master controller, all eight zones are ramped up to set point at a user-defined rate on power up.

The retransmit output from the master Series 988 is set so that $0 \mathrm{~V}=$ (dc) represents $0^{\circ} \mathrm{F}$ and $5 \mathrm{~V}=$ (dc) represents $800^{\circ} \mathrm{F}$. On the remote controllers, set the input 2 DIP switch to the position for the $0-5,1-5,0-10 \mathrm{~V}=$ (dc) process input. In the Input Menu, under the Input 2 prompt in己, select 0-5. The Remote Set Point prompt $r 5 P$ should be set to ON $\square 0$ and decimal $2 \sigma E[己]$ set to 0 . The range low $2 r L \mathcal{L}]$ and the range high 2 rHC parameters will establish the scaling for the remote set point input. Range low $2 \square \mathcal{L}$ ? should be set to 0 and range high 2 $r H 2$ should be set to 800 . To operate a specific zone ten degrees hotter than the others, increase the range low $2 \boxed{\Gamma L}$ to 10 and the range high $2 r \mathrm{HC}$ to 810 .

With remote set point $\quad \boldsymbol{\operatorname { S P }}$ enabled and local $\square$ selected under the Local-remote prompt $L-\boldsymbol{r}$ in the System Menu, the set point is adjusted using the up-arrow and down-arrow keys. Selecting remote $\square \boldsymbol{r}$ under the Local-remote prompt $L-r$, disables the up-arrow and down-arrow keys, allowing the set point value to be manipulated by the input 2 signal.

## Retransmit

## Requirements

Output 3 is used for the retransmit option. Choose either a milliamp (98
 range in the Output Menu.

## Overview

The retransmit feature can be used to transmit an analog signal representing the value of either input process variable or the target set point variable. The retransmit signal is factory configured as either a milliamp
 the type of retransmit signal the operator must take into account the input impedance of the device to be retransmitted to and the required signal type, either voltage or milliamps.

Typically applications might use the retransmit option to record one of the variables with a chart recorder or to generate a set point for other controls in a multi-zone application (see page 8.19).


Figure 8.21 -
Heat-treat oven with retransmit.

## Sample Applications

A Series 988 is being used to control the temperature of a heat-treat oven. The temperature of the process must be recorded on a chart recorder. The oven temperature range stays between $600^{\circ}$ and $900^{\circ} \mathrm{F}$. The chart recorder requires a $4-20 \mathrm{~mA}$ signal.

In the Output Menu OLPE set analog output Rout to Prei to tag the input 1 process value as the parameter to be retransmitted. Set retransmit low limit ArL to 600 to set the low range for the retransmit signal to 600. Set retransmit high limit $\operatorname{ArH}$ to 900 to set the high range for the retransmit signal to 900. Set retransmit calibrate offset $\boldsymbol{A C A L}$ to 0 , assuming there is no calibration offset required.

The retransmit output will be 4 mA until the oven temperature is greater than 600 degrees F , at which point the signal will increase with temperature to 20 mA at $900^{\circ} \mathrm{F}$ and will not exceed 20 mA .

## Slidewire Feedback

## Requirements

A slidewire configuration uses at least two inputs and two control out-

NOTE:
Outputs must be compatible with the slidewire valve actuators.


## Overview

The Series 988 can control the position of a valve with a slidewire feedback position indicator. The controller senses the resistance of the slidewire and compares it to the range low and range high settings to determine the valve position. The controller compares this to the percent output and takes action to match the two by opening or closing the valve.

Set the hunt hunt parameter to limit valve hunting. The value is set for the percent of output ( 0.0 to 100.0). When the valve is within this dead band, a change in output greater than half the hunt parameter is required to trigger action. Output 1 responds to "close" commands and output 2 responds to "open" commands.


Figure 8.23 -
Gas-fired furnace with slidewire feedback.

## Sample Application

A Series 988 controls the gas valve for a gas-fired furnace to heat treat large metal parts. First the controller must be "married" to the slidewire feedback from the valve actuator. To do this, first set the Input 2 prompt ind to slidewire SLid. Advance to the Learn Low Resistance prompt $L r \cap L$. Close the valve manually to the minimum resistance reading from the slidewire. Select YES in the upper display and press the Mode key mode to advance to the Learn High Resistance prompt LraH. Manually open the valve (maximum slidewire resistance). Select $Y E S$ in the upper display and press the Mode key moob. At this point both the high and low resistance values have been learned and stored in the range low 2 and range high 2 parameters.

You can also manually set the range low and range high values. From the slidewire specifications, determine the low and high resistance values and enter these at the Range Low $r \mathcal{L}$ ? and Range High $r \boldsymbol{H}$ ? prompts.

Once the control is operating, adjust the hunt hunt parameter, to minimize valve oscillations. The hunt parameter sets up a dead band on both sides of the current valve position. The desired valve position is then compared to the actual position. If the difference is greater than the one-half of the hunt value, the Series 988 repositions the valve to achieve the temperature set point. Once repositioning is complete, the dead band is recalculated for the new valve position.

# Chapter 9 Enhanced Software 

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Figure 9.2a - System heat-up profiles using three different control methods.

Figure 9.2b - The cascade feature allows one Series 988 controller to internalize the functions of two controllers.

## Cascade

## Requirements

Cascade control requires enhanced software and two analog inputs, input 1 to monitor the primary, or outer, loop and input 2 to monitor the secondary, or inner, loop. At least one control output is required to control the process.

## Overview

Cascade control can handle a difficult process with minimal overshoot, while reaching the set point quickly. This minimizes damage to system components and allows for oversizing heaters for optimal heat-up rates. Heater life is also extended by reducing thermal cycling of the heater.

Systems with long lag times between the energy source (heater, steam, etc.) and the measured process value cannot be controlled accurately or efficiently with a single control loop, because a lot of energy can build up before a response is detected. This
 can cause the system to overshoot the set point, which could damage the heater, product or heat transfer medium, such as a heat transfer fluid.

This graph illustrates a system with a long lag time. Curve A represents a single-control system with PID parameters that allow a maximum heat-up rate. Too much energy is introduced and the set point is overshot. In most long-lag-time systems the process value may never settle out to an acceptable error. Curve C represents a single-control system tuned to minimize overshoot. This results in unacceptable heat-up rates, with the final value taking hours to reach. Curve B shows a cascade system that limits the energy
 introduced into the system, allowing an optimal heat-up rate with minimal overshoot.

This drawing shows two controllers configured as a cascade system. The second controller generates the internal set point. The Series 988 effectively combines both controllers into a single package.

The primary controller measures the process in the outer, or primary, loop with input 1 and compares the value to the desired set point. The differ-
ence between the set point and the process temperature generates an internal percent output value for the second, or inner loop, controller. This value cannot be seen by the operator. This internal percent (\% int) output generates the internal set point for the secondary, or inner loop. The secondary loop uses this set point and the value of input 2 (typically attached to the heater sheath) to control the heat source temperature.

## Algorithm

The following formulas show how the primary control sends a set point (based on input 2 range-high and range-low values) to the secondary control. The secondary control uses this set point ( SP int) to generate a percent output (\% out) to the heater.
1.) $\%_{i n t}=$ PID Set A [In1 - SP]
2.) $\mathrm{SP}_{\text {int }}=(\mathrm{rH} 2-\mathrm{rL} 2) * \%_{\text {int }}+\mathrm{rL} 2$
3.) $\%_{\text {out }}=\operatorname{PID} \operatorname{Set} \mathrm{B}\left[\operatorname{In} 2-\mathrm{SP}_{\text {int }}\right]$

The critical parameters are the range settings for input 2 of the inner loop controller. The range-high value (rH2) is the maximum allowed set point for the secondary, or inner, loop. The range-low value (rL2) is the minimum allowed set point. In a system controlling a heater this would be the maximum and minimum desired sheath temperatures of the heater. Typically the range-low term is set below the ambient temperature. Otherwise the system could never fully cool down.

## Setup

When tuning a cascade system, the inner loop must be tuned first. In a heating system the inner loop is comprised of the output device and the input 2 sensor, which usually measures the heater sheath temperature. The output device controls a power switching device, which, in turn switches the heater. The set point for the inner loop is generated by the outer loop and will have a range between range low $2 r \operatorname{l}$ ) and range high 2 rHC.

Before tuning the inner loop you must make sure $r \mathrm{~L}$ ] and $r \mathrm{H}$ are set properly. Set the value of $r \leq 2$ slightly lower than the ambient temperature, otherwise the system will never fully cool down. Set $\square \mathrm{HC}$ to the maximum desired heat source temperature. The inner loop can be auto-tuned by setting $R U E$ to $P, d b$. While auto-tuning, the inner loop will be controlled in an ON/OFF mode at a set point equal to At SP $x$ rHC.

Once the inner loop, PID B, has completed auto-tuning, we can then autotune the outer loop, PID A. The outer loop will generate the set point for the inner loop. This is done by comparing the value of the input 1 sensor to the process set point, performing the control algorithm by using the values of $P, d R$, then generating a set point between $r(2)$ and $r H 2$.

The outer loop can be auto-tuned by setting $Q U \mathbb{U} t$ to $P, d R$. While autotuning, the outer loop will be controlled in an on/off mode at a set point equal to RESP x SP I. In a heating application, make sure the set point is set at a value above ambient temperature. In most cases, the auto-tuning feature will tune $[P, d \boldsymbol{P}$ for acceptable control. If not, you must then manually tune the outer loop.

Before beginning manual tuning, record the values of $P \mathrm{~Pb} \mid \boldsymbol{P}$ and $\widetilde{r E} / \mathbb{R}$ generated by the auto-tuning feature. The auto-tune for the outer loop will not generate a value for rA i8, because rate (derivative) in the outer loop seems to cause instability in most systems.

Start manual tuning by setting $[\mathcal{F} \mid 8]$ to 0.00 . Enter the desired process set point and let the system stabilize. Once the system stabilizes, observe the value of $\operatorname{Pr} \boldsymbol{D}$ in the Display Menu. If the $\operatorname{Pr} \boldsymbol{Z}$ value fluctuates, make the proportional band setting $\operatorname{Pb} \mid \boldsymbol{Q}$ wider until the $\operatorname{Pr}$ ] value stabilizes. Make adjustment $\left[\mathrm{Pb} / \mathbb{I}\right.$ in $5^{\circ}$ to $10^{\circ}$ increments, allowing time between adjustments for the system to stabilize.

Once $\operatorname{Pr} \boldsymbol{Z}$ has stabilized, observe percent power in the display loop. It should be stable, $\pm 10 \%$. At this point, the process temperature should also be stable, but will exhibit droop (stabilized below set point). The droop can be eliminated with reset of integral.

Start with a setting of 0.01 ; allow 10 minutes for the process temperature to come up to set point. If it has not, increase the setting to 0.05 and wait another 10 minutes. After this, double the reset setting until process value equals the set point. If the process becomes unstable, the reset value is too large. Decrease the setting until the process stabilizes.


Figure 9.5 - Lube oil tank with cascade control.

## Sample Application

A Series 988 controller is used to heat lube oil to $125^{\circ} \mathrm{F}$ with a screw-plugstyle heater. To protect the oil from breaking down and maximize its life, it is desirable to limit the maximum heater sheath temperature to $250^{\circ} \mathrm{F}$.

The Series 988 is ordered with two thermocouple inputs. Input 2, the inner loop in the cascade configuration, measures the heater sheath. Input 1, the outer loop, measures the lube oil temperature before it leaves the tank. The external set point is $125^{\circ}$. By setting range high $2 \sim \mathrm{rHC}$ to $250^{\circ}$ the set point for the heater sheath will be limited, thus extending the lube oil life.

## Differential

## Requirements

Two inputs and the enhanced software option are required.

## Overview

Differential control allows the Series 988 to control one process at a difference to another process. Input 2 acts as a remote set point input. However the displayed set point indicates the desired difference between input 1 and input 2 . The set point that input 1 will use is determined by the equation:
internal set point $=$ input $2+$ differential set point
The lower display shows the differential set point, which can be adjusted with the increment (up-arrow) and decrement (down-arrow) keys.

Please note that while in the differential control mode the internal set point for input 1 cannot be viewed and must be calculated with the equation.


Figure 9.7 - Water boiler with differential control.

## Sample Application

The most common application using differential control is to maintain water temperature in a boiler at a differential to the outside air temperature. A thermocouple at input 2 senses the outside air temperature and adjusts the internal set point to maintain the boiler water temperature 120 degrees higher. Substituting values we have: boiler temperature $=$ outside temperature $+120^{\circ}$.

In this application the system uses two type $J$ thermocouples: one to sense boiler water temperature (input 1) and one to sense the outside air temperature (input 2).

To configure the controller, first enable input 2 ( $\operatorname{set} \quad \operatorname{inc}$ to $\square \boldsymbol{u}$ ). To enable the differential control algorithm set the control prompt [ $[n \ell L$ in the Global Menu to differential $\boldsymbol{d}, \boldsymbol{F F}$. Press the DISPLAY key. The lower display will read 0 , indicating no differential between input 1 and input 2. Adjust the set point to 120 . The internal set point for input 1 is now equal to the input 2 value plus 120, which will maintain the boiler water temperature 120 degrees higher than the outside air temperature.

## Dual PID Sets

## Requirements

The Series 988 controller needs the enhanced software option to use dual PID sets.

## Overview

Standard software units have a single set of PID parameters. Units with enhanced software can use two independent sets of heat/cool PID parameters, PID A $P, d \boldsymbol{\beta}$ and PID B $P, d b$. To enable dual PID, enter the Global Menu and set the algorithm prompt $月 \mathrm{~L} 90$ to dual PID $P, d 己$. This second set of PID parameters enables the controller to switch between two sets of PIDs, to compensate for changes in the system characteristics. This need can arise from a variety of circumstances, such as significant set point changes (controlling at 250, then controlling at 750), operating a furnace with half a load versus a full load of steel, changing the speed of a conveyor through a curing oven or using different materials in an extruder.

Series 988 controllers can be configured to switch between PID A and PID B based on a process value, a set point value or the event input status.

- At $\boldsymbol{P}, \boldsymbol{d} \boldsymbol{Z}$ PID 2 Crossover Selection (Global Menu) select what will cause the switch:
- Proc Crossover Process Value, (input 1), PIDs will switch based on the crossover process value;
- StPt Crossover Set Point (1) Value, PIDs will switch at the crossover set point value, PID A used below the crossover point and PID B above;
- no no crossover.
- At E, I Event Input 1 or $\boldsymbol{E}, \boldsymbol{Z}$ Event Input 2 select $\boldsymbol{P}, \boldsymbol{d}$ :
- PID A is used when the event input switch is open;
- PID B when the event input switch is closed.
(Note: One event input is standard on all units, a second event input is an option.)


Figure 9.9 - Test chamber controlled with dual PID sets.

## Sample Application

A test engineer needs to control the temperature in a test chamber that can be operated at normal atmosphere or under vacuum conditions. If he tunes the controller for normal atmospheric conditions, when he reaches the portion of his test that requires a vacuum, he must stop the test and enter new PID parameters to maintain stable temperatures. The system characteristics are so very different, that one set of PIDs will not give satisfactory results under both normal and vacuum conditions.

The Series 988 solves this problem with the dual PID option. Auto-tuning PID A under normal atmospheric conditions, then auto-tuning PID B under vacuum conditions, establishes PID values for two sets of system characteristics. A pressure switch connected to the event input tells the controller when to switch between PID A and PID B, eliminating the need to change PID values manually.

## Duplex

## Requirements

The duplex control feature requires enhanced software and a process output.

## NOTE:

Duplex applications require a special valve.

## Overview

Certain systems require that a single process output control both heating and cooling outputs. A Series 988 controller configured with enhanced software and a process output can function as two separate outputs. With a 4 to 20 mA output the heating output will operate from 12 to 20 mA ( 0 to +100 percent) and the cooling output will operate from 12 to 4 mA ( 0 to 100 percent). In some cases this type of output is required by the device that the 988 controls, such as a three-way valve that opens one way with a 12 to 20 mA signal and opens the other way with a 4 to 12 mA signal. This feature reduces the overall system cost by using a single output to act as two outputs.


Figure 9.11 - Fluid sample container with duplex control.

## Sample Application

The system outlined above uses a three-way valve for heating and cooling a fluid sample. Coils surround the container holding the fluid. When the temperature needs to be raised, the signal to the valve will be between 12 and 20 mA , sending hot water through the coils. When cooling is required, the signal will be between 12 and 4 mA , sending cold water through the coils.

## Ratio

## Requirements

Ratio control requires enhanced software. Two analog inputs are required to monitor the process, and at least one output adjusts the controlled part of the process.

## Overview

This feature allows the Series 988 to control one process as a ratio of another process. This is especially useful in applications that mix two materials, whether steam, paint or food ingredients.

Input 2 of the controller measures the part of the process that is either uncontrolled or controlled by another device. The part of the process controlled by the 988 will be maintained at a level equal to the quantity measured at input 2 multiplied by the ratio term set by the user. Input 1 monitors the controlled part of the process.


Figure 9.13 - Mixing tank with ratio control.

## Sample Application

Blue pigment must be added to paint at a ratio of one part per 100 to create a mixed paint of the desired color. The uncolored paint flows into the mixer in an uncontrolled stream that is set manually and sensed by input 2. A motorized valve controls the flow of pigment, which is monitored by the flow sensor to input 1 . The flow rate of the uncolored paint determines the set point for the motorized valve that controls the pigment flow. If an operator needs to change the rate of flow for the uncolored paint, the set point will shift accordingly to maintain the correct ratio in the mixing tank.

The application engineer set up this feature in software by choosing ratio FAL 1 as the control [ntL parameter in the Global Menu. The set point value displayed was then a ratio value. He entered 0.01 to maintain an input 1 :input 2 ratio of $1: 100$.

## Appendix

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annunciator - A visual display that uses pilot lights to indicate the former or existing condition of several items in a system.
bumpless transfer - A smooth transition from auto (closed loop) to manual (open loop) operation. The control output(s) does not change during the transfer.
burst fire - A power control method that repeatedly turns on and off full ac cycles. Also called zero-cross fire, it switches close to the zero-voltage point of the ac sine wave. Variable-time-base burst fire selectively holds or transits ac cycles to achieve the desired power level.
calibration offset - An adjustment to eliminate the difference between the indicated value and the actual process value.
cascade - Control algorithm in which the output of one control loop provides the set point for another loop. The second loop, in turn, determines the control action.
closed loop - A control system that uses a sensor to measure a process variable and makes decisions based on that feedback.
cold junction - See junction, cold.
cold junction compensation - Electronic means to compensate for the effective temperature at the cold junction.
current transformer - A transformer designed for measuring electrical current.
dead band - The range through which a variation of the input produces no noticeable change in the output. In the dead band, specific conditions can be placed on control output actions. Operators select the dead band. It is usually above the heating proportional band and below the cooling proportional band.
default parameters - The programmed instructions that are permanently stored in the microprocessor software.
derivative - The rate of change in a process variable. Also known as rate. See PID.

Deutsche Industrial Norm (DIN) - A set of technical, scientific and dimensional standards developed in Germany. Many DIN standards have worldwide recognition.

DIN - See Deutsche Industrial Norm.
droop - In proportional controllers, the difference between set point and actual value after the system stabilizes.
duty cycle - The percentage of a cycle time in which the output is on.
external signal conditioner power supply - A dc voltage source that powers external devices.

## filter -

digital filter (DF) - A filter that slows the response of a system when inputs change unrealistically or too fast. Equivalent to a standard resistor-capacitor
(RC) filter.
digital adaptive filter - A filter that rejects high frequency input signal noise (noise spikes).
heat/cool output filter - A filter that slows the change in the response of the heat or cool output. The output responds to a step change by going to approximately $2 / 3$ its final value within the number of scans that are set.
form A - A single-pole, single-throw relay that uses only the normally open (NO) and common contacts. These contacts close when the relay coil is energized. They open when power is removed from the coil.
form B - A single-pole, single-throw relay that uses only the normally closed ( NC ) and common contacts. These contacts open when the relay coil is energized. They close when power is removed from the coil.
form $\mathbf{C}$ - A single-pole, double-throw relay that uses the normally open (NO), normally closed (NC) and common contacts. The operator can choose to wire for a Form A or Form B contact.
hunting - Oscillation of process temperature between the set point and the process variable.
hysteresis - A change in the process variable required to re-energize the control or alarm output. Sometimes called switching differential.
integral - Control action that automatically eliminates offset, or droop, between set point and actual process temperature. See reset, automatic.
isolation - Electrical separation of sensor from high voltage circuitry. Allows use of grounded or ungrounded sensing element.

Joint Industrial Standards (JIS) - A Japanese agency that establishes and maintains standards for equipment and components. Also known as JISC (Japanese Industrial Standards Committee), its function is similar to Germany's Deutsche Industrial Norm (DIN).

JIS - Joint Industrial Standards.
junction - The point where two dissimilar metal conductors join to form a thermocouple.
cold junction - Connection point between thermocouple metals and the electronic instrument. See reference junction.
grounded junction - Type of thermocouple probe in which the hot, or measuring junction, is an integral part of the sheath material. No electrical isolation is provided.
isolated junction - A form of thermocouple probe construction in which the measuring junction is fully enclosed in a protective sheath and electrically isolated from it. Commonly called an ungrounded junction.
reference junction - The junction in a thermocouple circuit held at a stable, known temperature (cold junction). Standard reference temperature is $32^{\circ} \mathrm{F}\left(0^{\circ} \mathrm{C}\right)$.
thermocouple junction - The point where the two dissimilar metal conductors join. In a typical thermocouple circuit, there is a measuring junction and a reference junction. See reference junction.
ungrounded junction - See isolated junction.
linearization, square root - The extraction of a linear signal from a nonlinear signal corresponding to the measured flow from a flow transmitter. Also called square root extraction.

Modbus (RTU) - Remote Terminal Unit.

NEMA $4 X$ - A NEMA specification for determining resistance to moisture infiltration. This rating certifies the controller as washable and corrosion resistant.
on/off - A method of control that turns the output full on until set point is reached, and then off until the process error exceeds the hysteresis.
open loop - A control system with no sensory feedback.
output - Control signal action in response to the difference between set point and process variable.
overshoot - The amount by which a process variable exceeds the set point before it stabilizes.

P control - Proportioning control.
PD control - Proportioning control with derivative (rate) action.

PDR control - Proportional derivative control with manual reset, used in fast responding systems where the reset causes instabilities. With PDR control, an operator can enter a manual reset value that eliminates droop in the system.

PI control - Proportioning control with integral (automatic reset) action.

PID - Proportional, integral, derivative. A control mode with three functions: proportional action dampens the system response, integral corrects for droop, and derivative prevents overshoot and undershoot.
process variable - The parameter that is controlled or measured. Typical examples are temperature, relative humidity, pressure, flow, fluid level, events, etc. The high process variable is the highest value of the process range, expressed in engineering units. The low process variable is the lowest value of the process range.
proportional band (PB) - A range in which the proportioning function of the control is active. Expressed in units, degrees or percent of span. See PID.
proportional control - A control using only the P (proportional) value of PID control.
rate band - A range in which the rate function of a controller is active. Expressed in multiples of the proportional band. See PID.
ratio - A method by which the controller measures the flow of an uncontrolled variable and uses a proportion of it to control the flow of a second variable.
reference junction - See junction.
reset - Control action that automatically eliminates offset, or droop, between set point and actual process tem-
perature. Also see integral.
automatic reset - The integral function of a PI or PID temperature controller that adjusts the process temperature to the set point after the system stabilizes. The inverse of integral.
automatic power reset - A feature in latching limit controls that does not recognize power outage as a limit condition. When power is restored, the output is reenergized automatically, as long as the temperature is within limits.
manual reset - 1) A feature on a limit control that requires human intervention to return the limit to normal operation after a limit condition has occurred. 2) The adjustment of a proportional control to raise the proportional band to compensate for droop.
no key reset - A method for resetting the controller's memory (for instance, after an EPROM change).
resistance temperature detector (RTD) - A sensor that uses the resistance temperature characteristic to measure temperature. There are two basic types of RTDs: the wire RTD, which is usually made of platinum, and the thermistor, which is made of a semiconductor material. The wire RTD is a positive temperature coefficient sensor only, while the thermistor can have either a negative or positive temperature coefficient.
retransmit output - An analog output signal that may be scaled to represent the process value or set point value.

RTD - See resistance temperature detector.
slidewire feedback - A method of controlling the position of a valve. It uses a potentiometer to vary resistance and indicate position of the valve.
switching sensitivity - In on/off control, the temperature change necessary to change the output from full on to full off. See hysteresis.
thermal system - A regulated environment that consists of a heat source, heat transfer medium or load, sensing device and a control instrument.
thermocouple ( $\mathbf{t} / \mathbf{c}$ ) - A temperature sensing device made by joining two dissimilar metals. This junction produces an electrical voltage in proportion to the difference in temperature between the hot junction (sensing junction) and the leadwire connection to the instrument (cold junction).
thermocouple break protection - The ability of a control to detect a break in the thermocouple circuit and take a predetermined action.
three-mode control - Proportioning control with integral (reset) and derivative (rate). Also see PID.
time proportioning control - A method of controlling power by varying the on/off duty cycle of an output. This variance is proportional to the difference between the set point and the actual process temperature.
zero cross - Action that provides output switching only at or near the zero-voltage crossing points of the ac sine wave. See burst fire.
zero switching - See zero cross.

## Specifications <br> (1234)

## Control Mode

- Dual input, quad output, optional retransmit of set point or process variable.
- Programmable direct and reverse acting control outputs.
- One-step auto-tuning.


## Operator Interface

- Local/remote set point capability.
- Dual, 4-digit LED displays: upper, 0.4 " ( 10 mm ); lower, 0.3 " (8mm).
- Mode, Auto/Man, Display, Up and Down keys.

Input

- Contact input for software function select.
- Type J, K, T, N, C(W5) 2 , D(W3) $)_{2}$, E, R, S, B, Pt $2_{2}$ thermocouple, $1^{\circ}$ or $0.1^{\circ}$ RTD.
- $0-50 \mathrm{mV}=$ (dc), $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, 0-5 \mathrm{~V}=$ (dc), $1-5 \mathrm{~V}=$ (dc), 0-10V $=$ (dc) process.
- Slidewire, digital event input or heater current options.
- Sensor break protection de-energizes control output to protect system or selectable bumpless transfer to manual operation. Latching or non-latching.
- ${ }^{\circ} \mathrm{F}$ or ${ }^{\circ} \mathrm{C}$ display or process units, user selectable.


## Sensor Ranges

| J t/c: | 32 | to | $1500^{\circ} \mathrm{F}$ | or | 0 | to | $816^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| K t/c: | -328 | to | $2500^{\circ} \mathrm{F}$ | or | -200 | to | $1371{ }^{\circ} \mathrm{C}$ |
| T t/c: | -328 | to | $750{ }^{\circ} \mathrm{F}$ | or | -200 | to | $399{ }^{\circ} \mathrm{C}$ |
| N t/c: | 32 | to | $2372{ }^{\circ} \mathrm{F}$ | or | 0 | to | $1300^{\circ} \mathrm{C}$ |
| R t/c: | 32 | to | $3200^{\circ} \mathrm{F}$ | or | 0 | to | $1760^{\circ} \mathrm{C}$ |
| St/c: | 32 | to | $3200^{\circ} \mathrm{F}$ | or | 0 | to | $1760^{\circ} \mathrm{C}$ |
| B t/c: | 1598 | to | $3300^{\circ} \mathrm{F}$ | or | 870 | to | $1816^{\circ} \mathrm{C}$ |
| Et/c: | -328 | to | $1470{ }^{\circ} \mathrm{F}$ | or | -200 | to | $799^{\circ} \mathrm{C}$ |
| C t/c (W5) ${ }_{2}$ : | 32 | to | $4200^{\circ} \mathrm{F}$ | or | 0 | to | $2316^{\circ} \mathrm{C}$ |
| D t/c (W3) ${ }_{2}$ : | 32 | to | $4200^{\circ} \mathrm{F}$ | or | 0 | to | $2316^{\circ} \mathrm{C}$ |
| Pt $2_{2}$ : | 32 | to | $2543{ }^{\circ} \mathrm{F}$ | or | 0 | to | $1395^{\circ} \mathrm{C}$ |
| $1^{\circ}$ RTD (JIS): | -328 | to | $1166^{\circ} \mathrm{F}$ | or | -200 | to | $630^{\circ} \mathrm{C}$ |
| $1^{\circ}$ RTD (DIN): $0.1^{\circ} \mathrm{RTD}$ | -328 | to | $1472{ }^{\circ} \mathrm{F}$ | or | -200 | to | $800^{\circ} \mathrm{C}$ |
| (JIS and DIN):- | -99.9 | to | $999.9^{\circ} \mathrm{F}$ | or | -73.3 | to | $537.7^{\circ} \mathrm{C}$ |
| $0-5 \mathrm{~V}=$ (dc): | -999 | to | 9999 |  |  |  |  |
| 1-5V $=$ (dc): | -999 | to | 9999 |  |  |  |  |
| $0-10 \mathrm{~V}=$ (dc): | -999 | to | 9999 |  |  |  |  |
| 0-20mA: | -999 | to | 9999 |  |  |  |  |
| 4-20mA: | -999 | to | 9999 |  |  |  |  |
| $0-50 \mathrm{mV}=$ (dc): | :-999 | to | 9999 |  |  |  |  |
| Slidewire: | 100 | to | $1200 \Omega$ |  |  |  |  |
| Current: | 0 | to | 50A |  |  |  |  |
| Potentiometer: | 0 | to | $1200 \Omega$ |  |  |  |  |
| Output Option |  |  |  |  |  |  |  |

- Solid-state relay, 0.5A @ 24V~ (ac) min., 253V~ (ac) max., opto-isolated, burst fire. With or without contact suppression.
- Open collector: Max. voltage $42 \mathrm{~V}=$ (dc), max. current 1A.
- Switched dc signal: Min. turn-on voltage of $3 \mathrm{~V}=$ (dc) into min. $500 \Omega$ load; max. On voltage not greater than $32 \mathrm{~V}=$ (dc) into an infinite load, isolated.
- Electromechanical relay ${ }_{1}$, Form C, 5A @ 120/240V~ (ac), 6A @ 28V=: (dc), 1/8 hp. @ 120V~ (ac) or 125VA @ 120V~ (ac). With or without contact suppression. Off-state output impedance with RC suppression is $20 \mathrm{k} \Omega$.
- Process, $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}$ into $800 \Omega$ maximum, $0-$ $5 \mathrm{~V}=$ (dc), $1-5 \mathrm{~V}=$ (dc) or $0-10 \mathrm{~V}=$ (dc) into $1 \mathrm{k} \Omega$ minimum $_{1}$, reverse acting, isolated.
- Electromechanical relay, Form A/B, 5A @ 120/240V~ (ac), 6A @ 28V=. (dc), 1/8 hp. @ 120V~ (ac) or 125VA @ 120V~ (ac). Without contact suppression.
- External transmitter power supply, $5 \mathrm{~V} \pm 5 \%$ @ 30 mA , $12 \mathrm{~V} \pm 5 \%$ @ 30 mA or $20 \mathrm{~V} \pm 5 \%$ @ 30mA.
- EIA/TIA-232 communications or EIA/TIA-485, EIA/TIA422 communications, opto-isolated.


## Accuracy

- Calibration accuracy and sensor conformity: $\pm 0.1 \%$ of span, $\pm 1 \mathrm{LSD}, 77^{\circ} \mathrm{F} \pm 5^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C} \pm 3^{\circ} \mathrm{C}\right)$ ambient and rated line voltage $\pm 10 \%$.
- Accuracy span: $1000^{\circ} \mathrm{F}\left(540^{\circ} \mathrm{C}\right)$ minimum.
- Temperature stability: $\pm 0.2^{\circ} \mathrm{F} /{ }^{\circ} \mathrm{F}\left(0.1^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{C}\right)$ change in ambient.
- Voltage stability: $\pm 0.01 \%$ of span $/ \%$ of rated line voltage.


## Agency Approvals

- UL, C-UL File \#43684
- CE: 89/336/EEC Electromagnetic Compatibility Directive.
EN 50081-2: 1994 Emissions.
EN 50082-2: 1995 Immunity.
- 73/23/EEC Low-Voltage Directive.

EN 61010-1: 1993 Safety.

- NEMA 4X

Terminals

- \#6 compression universal head screws (tighten to 5 inch/pounds maximum), accepts 20-14 gauge wire.


## Line Voltage/Power

- 100 to $240 \mathrm{~V} \sim_{1}$ (ac) $+10 \% /-15 \%, 50 / 60 \mathrm{~Hz}, \pm 5 \%$.
- 24 to $28 \mathrm{~V} \approx_{1}$ (ac/dc) $+10 \% /-15 \%, 50 / 60 \mathrm{~Hz}, \pm 5 \%$.
- 16VA maximum.
- Fused internally (factory replaceable only) Slo-Blo® type (time-lag): 2A, 250 V for high-voltage versions; $5 \mathrm{~A}, 250 \mathrm{~V}$ for low-voltage versions.
- Non-volatile memory retains data if power fails.


## Operating Environment

- 32 to $149^{\circ} \mathrm{F}\left(0\right.$ to $65^{\circ} \mathrm{C}$ ), 0 to $90 \% \mathrm{RH}$, non-condensing.


## Storage Temperature

- -40 to $185^{\circ} \mathrm{F}\left(-40\right.$ to $\left.85^{\circ} \mathrm{C}\right)$.


## Mechanical

- 1/8 DIN panel mount, NEMA 4X (IP65 equivalent) front panel.
- Overall width $x$ height $x$ depth: horizontal - 4.03" x 2.18 " x 4.74"
( $102 \mathrm{~mm} \times 55 \mathrm{~mm} \times 120 \mathrm{~mm}$ );
vertical - 2.18" x 4.03" x 4.74"
( $55 \mathrm{~mm} \times 102 \mathrm{~mm} \times 120 \mathrm{~mm}$ ).
- Depth behind panel; 4.06" (103mm).
- Weight: less than or equal to 14.0 oz ( 0.40 kg ).

Sample/Update Rates

- 1 input: 10 Hz .
- 2 inputs: 5 Hz .
- Retransmit: 1 Hz .
- Remote set point: 1 Hz .
- PID: 10 Hz .
- Outputs: 10 Hz .
- Display: 2 Hz .
- Alarm Outputs: 1 Hz

Resolution

- Inputs: 16 bits.
- Outputs: 12 bits.
${ }^{1}$ Electromechanical relays are warranted for 100,000 closures only. Solid-state switching devices are recommended for applications requiring fast cycle times or extended service life.
${ }^{2}$ Not an ANSI symbol.

The Watlow Series 988 is warranted to be free of defects in material and workmanship for 36 months after delivery to the first purchaser for use, providing that the units have not been misapplied. Since Watlow has no control over their use, and sometimes misuse, we cannot guarantee against failure. Watlow's obligations hereunder, at Watlow's option, are limited to replacement, repair or refund of purchase price, and parts which upon examination prove to be defective within the warranty period specified. This warranty does not apply to damage resulting from transportation, alteration, misuse or abuse.

## Watlow Controls

Watlow Controls is a division of Watlow Electric Mfg. Co., St. Louis, Missouri, a manufacturer of industrial electric heating products since 1922. Watlow begins with a full set of specifications and completes an industrial product that is manufactured totally inhouse, in the U.S.A. Watlow products include electric heaters, sensors, controls and switching devices. The Winona operation has been designing solid state electronic control devices since 1962, and has earned the reputation as an excellent supplier to original equipment manufacturers. These OEMs depend upon Watlow Controls to provide compatibly engineered controls which they can incorporate into their products with confidence. Watlow Controls resides in a 100,000-square-foot marketing, engineering and manufacturing facility in Winona, Minnesota.

## Returns

1. Call Watlow Customer Service, (507) 454-5300, for a Return Material Authorization (RMA) number before returning any item for repair. We need this information:

- Ship to address
- Bill to address
- Contact name
- Phone number
- Ship via
- Your P.O. number
- Symptoms and/or special instructions
- Name and phone number of person returning the material.

2. Prior approval and an RMA number, from the Customer Service Department, is needed when returning any unused product for credit. Make sure the RMA number is on the outside of the carton, and on all paperwork returned. Ship on a Freight Prepaid basis.
3. After we receive your return, we will examine it and determine the cause for your action.
4. In cases of manufacturing defect, we will enter a repair order, replacement order, or issue credit for material. A 20 -percent restocking charge is applied for all returned stock controls and accessories.
5. If the unit is unrepairable, it will be returned to you with a letter of explanation. Repair costs will not exceed 50 percent of the original cost.

## Shipping Claims

When you receive your Watlow control, examine the package for any signs of external damage it may have sustained enroute. If there is apparent damage either outside the box or to its contents, make a claim with the shipper immediately. Save the original shipping carton and packing material.
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output $1 \underline{2.12}$
output $2 \underline{2.13}$
$0-10 \mathrm{~V}=$ (dc) process wiring
input 12.8
input $2 \underline{2.9}$
output $1 \underline{2.12}$
output $2 \underline{2.13}$
$0-20 \mathrm{~mA}$ process wiring input $1 \underline{2.8}$
input 22.9
output $1 \underline{2.12}$
output $2 \underline{2.13}$
$0-50 \mathrm{mV}$ (high impedance) wiring input $1 \underline{2.8}$ input $2 \underline{2.9}$
$1-5 \mathrm{~V}=$ (dc) process wiring
input 12.8
input 22.9
output $1 \underline{2.12}$
output $2 \underline{2.13}$
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$$

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5 SD（set point 2） 5.3
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Figure A. 10 The Series 988 Map.

NOTE:
This is a complete listing of all Series 988 prompts.

Not all prompts will appear on your control. They are dependent on your configuration and model number.

## To navigate:

Press isplav to return to the Display Loop from any location and to advance through the Display Loop.

Press $\boldsymbol{\square}$ or to move between the menus.

Press moos to advance through a menu.

Hold mone while pressing to move backwards through the menus.

Press $\boldsymbol{\square}$ or to select prompt values.

NOTE:
The controller will not default back to normal display while in the Factory Menu. All outputs are disabled while in this menu.


## Ordering Information

## (1237)

${ }^{1}$ Electromechanical relays warranted for 100,000 closures only. Solid-state switching devices recommended for applications requiring fast cycle times or extended service life.
${ }^{2} \mathrm{~A}$ Current Transformer input cannot be used in conjunction with a process output installed on output 1.
$\mathrm{Slo}^{-\mathrm{Blo}^{\star}}$ is a registered trademark of Littelfuse, Inc.

To order, complete the code number to the right with the information below:
To order, complete the code number to the right with the information below:

Series 988: a single-channel, temperature/process controller, 1 analog input, 1 digital input, 1 analog or digital input, 4 outputs.
Power Supply \& Mounting
$6=24$ to $28 \mathrm{~V} \approx(\mathrm{ac} / \mathrm{dc})$ nominal, vertical mounting
$7=24$ to $28 \mathrm{~V} \approx(\mathrm{ac} / \mathrm{dc})$ nominal, horizontal mounting
$8=100$ to $240 \mathrm{~V} \approx$ (ac/dc) nominal vertical mounting
$9=100$ to $240 \mathrm{~V} \approx$ (ac/dc) nominal horizontal mounting

## Software

A = Standard
B = Enhanced (Includes cascade, ratio, | duplex, dual PID set)
Input 1
1 = Thermocouple only (Excluding Type B, R, and S)
2 = Universal signal conditioner
Input 2
= None
$=$ Thermocouple only (Excluding Type B, R, and S)
= Universal signal conditioner
= Slidewire feedback
= Current transformer ${ }^{2}$
= Digital contact event (One digital event is standard on all units)

## Output 1

$\mathrm{B}=$ Solid-state relay, Form A, 0.5 A , with RC suppression ( $\mathrm{NO} \& \mathrm{C}$ )
C = Switched dc or open collector, isolated
D = Electromechanical relay ${ }^{1}$, Form C, 5A with RC suppression
$\mathrm{E}=$ Electromechanical relay ${ }^{1}$, Form C, 5A without contact suppression
$\mathrm{F}=$ Universal process, $0-5 \mathrm{~V}=$ (dc), $1-5 \mathrm{~V}=$ (dc), $0-10 \mathrm{~V}=$ (dc), $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}$, isolated
K = Solid-state relay, Form A, 0.5A, without contact suppression (NO \& C)
Output 2
$\mathrm{A}=$ None
B = Solid-state relay, Form A, 0.5A, with RC suppression ( $\mathrm{NO} \& \mathrm{C}$ )
C = Switched dc or open collector, isolated
D = Electromechanical relay ${ }^{1}$, Form C, 5 A with RC suppression (NO, NC \& C)
E = Electromechanical relay ${ }^{1}$, Form C, 5A without contact suppression (NO, NC \& C)
$\mathrm{F}=$ Universal process $0-5 \mathrm{~V}=$ (dc), $1-5 \mathrm{~V}=$ (dc), $0-10 \mathrm{~V}=$ (dc), $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}$, isolated
$\mathrm{K}=$ Solid-state relay, Form A, 0.5 A , without contact suppression (NO \& C)
$\mathrm{T}=$ External signal conditioner power supply, 5, 12 or $20 \mathrm{~V}=$ (dc) @ 30 mA
Output 3
$\mathrm{A}=$ None
$B=$ Solid-state relay, Form A, 0.5 A , with RC suppression ( $\mathrm{NO} \& \mathrm{C}$ )
C = Switched dc or open collector, isolated
$J=$ Electromechanical relay ${ }^{1}$, Form A or B, 5 A without contact suppression (NO or NC)
K = Solid-state relay, Form A, 0.5A without contact suppression (NO \& C)
$\mathrm{M}=$ Retransmit, $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}$
$\mathrm{N}=$ Retransmit, $0-5 \mathrm{~V}=$ (dc), $1-5 \mathrm{~V}=$ (dc), $0-10 \mathrm{~V}=$ (dc)
$\mathrm{T}=$ External signal conditioner power supply, 5, 12 or $20 \mathrm{~V}=$ (dc) @ 30 mA

## Output 4

= None
$B=$ Solid-state relay, Form A, 0.5 A , with RC suppression ( $\mathrm{NO} \& \mathrm{C}$ )
C = Switched dc or open collector, isolated
D = Electromechanical relay ${ }^{\wedge}$, Form C, 5A with RC suppression (NO, NC \& C)
E = Electromechanical relay ${ }^{1}$, Form C, 5 A without contact suppression (NO, NC \& C)
$=$ Solid-state relay, Form A, 0.5 A without contact suppression (NO \& C)
$=$ EIA/TIA-232 communications, opto-isolated
= EIA/TIA-485 / EIA/TIA-422 communications, opto-isolated
$\mathrm{T}=$ External signal conditioner power supply, 5, 12 or $20 \mathrm{~V}=$ (dc) @ 30 mA
U = EIA/TIA-485 / EIA/TIA-232 communications, opto-isolated

## Display

$\begin{array}{ll}G G=\text { Green/Green displays } & \text { RR }=\text { Red/Red displays } \\ G R=G r e e n / R e d ~ d i s p l a y s ~ & X X=\text { Custom overlays or default settings } \\ R G=\text { Red/Green displays } & \end{array}$

# Declaration of Conformity 

## Series 986, 987, 988, 989 ( $\in 96$

watlow controls
1241 Bundy Boulevard
Winona, Minnesota 55987 USA


| Erklärt, daß das folgende Produkt: Deutsch |  |  |
| :---: | :---: | :---: |
| Beschreibung: <br> Modellnummer(n): |  | Serie 986, 987, 988, 989 |
|  |  | 98 (678 oder 9) (beliebiger Buchstabe) - (1 oder 2) (01234 oder 5) (BCDEF oder K) (A B C D E F K oder T) - (A B C J K M N oder T) (ABCDEKRS oder T ) ( 2 beliebige Buchstaben) |
| Klassifikation: |  | Regelsystem, Installationskategorie II, Emissionsgrad II |
| Nennspannung: |  | 100 bis $240 \mathrm{~V} \sim(\mathrm{ac})$ oder 24 bis $28 \mathrm{~V}=$ (ac/dc) |
| Nennfrequenz: |  | $50 / 60 \mathrm{~Hz}$ |
| Stromverbrauch: |  | Max. 16 VA |
| Erfüll die wichtigsten Normen der folgenden Anweisung(en) der Europäischen |  |  |
| Union unter Verwendung der untenstehenden einschlägigen Dokumente: 89/336/EEC Elektromagnetische Übereinstimmungsanweisung |  |  |
| EN 50082-2: | 1995 | EMC-Rahmennorm für Störsicherheit, Teil 2: Industrielle Umwelt |
| EN 61000-4-2: | 1995 | Elektrostatische Entladung |
| EN 61000-4-4: | 1995 | Elektrische schnelle Stöße |
| ENV 50140: | 1994 | Strahlungsimmunität |
| ENV 50141: | 1994 | Leitungsimmunität |
| ENV 50204: | 1995 | Mobiltelefon |
| EN 50081-2: | 1994 | EMC-Rahmennorm für Emissionen, Teil 2: Industrielle Umwelt |
| EN 55011: | 1991 | Beschränkungen und Methoden der Messung von Funkstörungsmerkmalen industrieller, wissenschaftlicher und medizinischer Hochfrequenzgeräte (Klasse A) |
| EN 61000-3-2: 1995 |  | Grenzen der Oberwellenstromemissionen |
| EN 61000-3-3: 1995 |  | Grenzen der Spannungsschwankungen und Flimmern |
| 72/23/EEC Niederspannungsrichtlinie zu entsprechen |  |  |
| EN 61010-1: | 1993 | Sicherheitsrichtlinien für Elektrogeräte zur Messung, zu Steuerung und im Labor, Teil 1: Allgemeine Richtlinien |



| Erwin D. Lowell | Winona, Minnesota, USA |
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